ModelArts

User Guide (Lite Server)

Issue 01

Date 2025-02-13





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Before You Start

1.1 Using Lite Server

ModelArts Lite Server provides various xPU bare metal servers (BMSs), allowing you to install and deploy third-party software such as AI frameworks and applications as user **root**. To create a BMS, you only need to configure the specifications, image, network, and key pairs.

This document helps you understand how to use Lite Server.

Resource provisioning

Resource configuration

Resource use

Resource management

Log in to your server and run a training or inference job.

Starting or stopping a server status

Configure access authorization.

Create a VPC.

Create a key pair.

Resource management

Viewing server details

Starting or stopping a server status

Changing the OS

Monitoring resources

Releasing resources

Figure 1-1 Process for using Lite Server

1. Purchasing resources

Purchase resources first.

- Contact the customer manager to determine a resource solution. Apply for the required resource specifications since certain specifications are restricted.
- b. The default resources provided by Huawei Cloud, such as elastic cloud server (ECS), elastic IP (EIP), and Scalable File Service (SFS), may not meet your requirements. Submit a service ticket to increase resource quota.

- c. Grant the required basic permissions to the IAM user.
- d. ModelArts needs to access other dependent services. Create an agency for ModelArts.
- e. When purchasing resources, you need to select a virtual private cloud (VPC) for network communication. You can use an existing VPC or create one.
- f. When you use key pairs to log in to the BMS, use an existing key pair or create one.
- g. Purchase resources on the ModelArts console.
- 2. Configuring resources

Configure the network, storage, and software environment.

3. Using resources

Log in to the server for model training and inference. For details, see **Using Lite Server Resources**.

4. Managing resources

Lite Server allows you to start, stop, and switch OSs. You can manage resources on the ModelArts console.

Table 1-1 Terms

Term	Description
BMS	Combining VM scalability with physical server performance, BMS provides dedicated cloud servers. These servers are designed to meet the demands of computing performance and data security for core databases, critical applications, high-performance computing (HPC), and big data.
	After you purchase Lite Server on the ModelArts console, a BMS corresponding to it will be created on the BMS console as Lite Server is a BMS. You can mount disks and bind EIPs on the BMS console.
	For more information about bare metal servers, see Bare Metal Server .
xPU	Graphics processing unit (GPU) or neural network processing unit (NPU).
	GPUs are used to accelerate the training and inference of deep learning models.
	NPUs are used to accelerate neural network computing. Compared with GPUs, NPUs feature higher efficiency and lower power consumption at neural network computing.
Key Pair	You can log in to an elastic server using only an SSH key pair. Therefore, you do not need worry about password interception, cracking, and leakage.
	NOTE To ensure ECS security, private keys that are not managed by Huawei Cloud can be downloaded only once. Keep your downloaded private keys properly.

Term	Description
VPC	A VPC is a logically isolated, configurable, and manageable virtual network. It helps improve the security of cloud resources and simplifies network deployment. Within your own VPC, you can create security groups and VPNs, configure IP address ranges, and specify bandwidth sizes by customizing security groups, VPNs, IP address ranges, and bandwidth. This simplifies network management. You can also customize access rules to control BMS access within a security group and across different security groups to enhance BMS security. For details, see Virtual Private Cloud.

1.2 High-Risk Operations

To avoid adverse impacts on ModelArts Lite Server, you must perform high-risk operations according to operation guides during the routine O&M.

Risky operations fall into three levels:

- High: Such operations may cause service failures, data loss, system maintenance failures, and system resource exhaustion.
- Medium: Such operations may cause security risks and reduce service reliability.
- Low: Such operations include high-risk operations other than those of a high or medium risk level.

Table 1-2 High-risk operations

Object	Operation	Risk	Severity	Solution
OS	Upgrade or modify the OS kernel or driver.	The driver and kernel versions may not be compatible. As a result, the OS cannot be started or basic functions are unavailable. For example, aptget upgrade is high-risk command.	High	Contact Huawei technical support.

Object	Operation	Risk	Severity	Solution
	Switch or reset OS.	The EVS system ID is changed. As a result, the EVS system disk cannot be scaled out, and message "The order is expired. The capacity cannot be expanded. Renew the order." is displayed.	Medium	Mount an EVS or SFS disk for capacity expansion.

1.3 Mapping Between Compute Resources and Image Versions

Lite Server provides multiple NPU and GPU images. You can learn about the supported images and details before purchasing them.

Images Supported by NPU Snt9 BMS

Image name: ModelArts-Euler2.8_Aarch64_Snt9_C78

Table 1-3 Image details

Туре	Version Details
OS	EulerOS 2.0 (SP8)
Kernel version	4.19.36-vhulk1907.1.0.h619.eulerosv2r8.aarch64
Architecture type	aarch64
mlnx-ofed-linux	21.0.2

Images Supported by NPU Snt9B BMS

• Image name: EulerOS2.10-Arm-64bit-for-Snt9B-BareMetal-with-23.0.6-7.1.0.9.220-CANN7.0.1.5

Table 1-4 Image details

Туре	Version Details
OS	EulerOS 2.10

Туре	Version Details
Kernel version	Linux 4.19.90- vhulk2211.3.0.h1543.eulerosv2r10.aarch64
Architecture type	aarch64
Firmware version	7.1.0.9.220
npu-driver	23.0.6
Ascend-cann-toolkit	7.0.1.5
cann-kernels	7.0.1.5
Ascend-mindx- toolbox	5.0.1.1
Docker	24.0.7
Ascend-docker- runtime	5.0.1.1
MindSpore Lite	2.1.0-cp37-cp37m
Mpich	3.2.1

• Image name: HCE2.0-Arm-64bit-for-Snt9B-BareMetal-with-23.0.6-7.1.0.9.220-CANN7.1.0.5

Table 1-5 Image details

Туре	Version Details
OS	HCE2.0
Kernel version	Linux 5.10.0-60.18.0.50.r865_35.hce2.aarch64
Architecture type	aarch64
Firmware version	7.1.0.9.220
npu-driver	23.0.6
Ascend-cann-toolkit	7.0.1.5
cann-kernels	7.0.1.5
Ascend-mindx- toolbox	5.0.1.1
Docker	18.09
Ascend-docker- runtime	5.0.1.1
MindSpore Lite	2.1.0-cp37-cp37m

Туре	Version Details
Mpich	4.1.3

Images Supported by GP Ant8 BMS

• Image name: Ubuntu-20.04-for-Ant8-with-RoCE-and-NVIDIA-525-CUDA-12.0-Uniagent

Table 1-6 Image details

Туре	Version Details
OS	Ubuntu 20.04 server 64bit
Kernel version	5.4.0-144-generic
Architecture type	x86
Driver version	525.105.17
cuda	12.0
container-toolkit	1.13.3-1
fabricmanager	525.105.17
mlnx-ofed-linux	5.8-2.0.3.1-ubuntu20.04-x86_64
peer-memory-dkms	1.2-0
libnccl2	2.18.1
nccl-test	v.2.13.6
docker	20.10.23
RoCE route configuration	Yes

 Image name: Ubuntu-20.04-for-Ant8-with-RoCE-and-NVIDIA-515-CUDA-11.7-Uniagent (CN North-Ulanqab1, CN North-Beijing4, and CN North-Ulanqab-Auto1)

Table 1-7 Image details

Туре	Version Details
OS	Ubuntu 20.04 server 64bit
Kernel version	5.4.0-144-generic
Architecture type	x86
Driver version	515.105.01

Туре	Version Details
cuda	11.7
container-toolkit	1.13.3-1
fabricmanager	515.105.01-1
mlnx-ofed-linux	5.8-2.0.3.1-ubuntu20.04-x86_64
peer-memory-dkms	1.2-0
libnccl2	2.14.3
nccl-test	v.2.13.6
docker	20.10.23
RoCE route configuration	Yes

Images Supported by GP Vnt1 BMS

□ NOTE

For Vnt1, the specifications in CN North-Beijing4, CN North-Beijing1, and CN East-Shanghai1 are the same. However, the product configuration and release time differ. As a result, the images cannot be shared.

 Image name: Ubuntu-18.04-for-BareMetal-Vnt1-p3-with-NVIDIA-470-CUDA-11.4-Uniagent (only for CN North-Beijing1, CN North-Beijing4, and CN South-Guangzhou1)

Table 1-8 Image details

Туре	Version Details
OS	Ubuntu 18.04 server 64bit
Kernel version	4.15.0-45-generic
Architecture type	x86
Driver version	470.182.03
cuda	11.4
container-toolkit	1.15.01
mlnx-ofed-linux	5.7-1.0.2.1-ubuntu18.04-x86_64
libnccl2	2.10.3-1
nccl-test	v2.13.9
docker	24.0.2

• Image name: Ubuntu-18.04-for-BareMetal-Vnt1-p6-with-NVIDIA-470-CUDA-11.4-Uniagent (only for CN East-Shanghai1)

Table 1-9 Image details

Туре	Version Details
OS	Ubuntu 18.04 server 64bit
Kernel version	4.15.0-45-generic
Architecture type	x86
Driver version	470.182.03
cuda	11.4
container-toolkit	1.15.01
mlnx-ofed-linux	5.7-1.0.2.1-ubuntu18.04-x86_64
libnccl2	2.10.3-1
nccl-test	v2.13.9
docker	24.0.2

• Image name: Euler2.9-X86-for-Vnt1-BareMetal (only for CN North-Beijing4 and CN East-Shanghai1)

Table 1-10 Image details

Туре	Version Details
OS	EulerOS 2.9 64bit
Architecture type	x86

 Image name: CentOS-7.9-64bit-for-BareMetal-Vnt1-with-NVIDIA-515-CUDA-11.7-Uniagent (only for CN North-Beijing1, CN North-Beijing4, and CN South-Guangzhou1)

Table 1-11 Image details

Туре	Version Details
OS	CentOS 7.9 64bit
Architecture type	x86

Images supported by GPU Ant1 BMS

Image name: Ubuntu-20.04-x86-for-Ant1-BareMetal-with-RoCE-and-GP-515-CUDA-11.7-AIGC (only for CN North-Beijing4 and CN North-Ulangab 1)

Table 1-12 Image details

Туре	Version Details
OS	Ubuntu 20.04 server 64bit
Architecture type	x86
RoCE route configuration	Automatic configuration is not supported. You need to configure it yourself after the image is created.

• Image name: Ubuntu-20.04-x86-for-Ant1-BareMetal-with-RoCE-and-NVIDIA-525-CUDA-12.0-AIGC (only for CN North-Ulanqab1)

Table 1-13 Image details

Туре	Version Details
OS	Ubuntu 20.04 server 64bit
Architecture type	x86
RoCE route configuration	Automatic configuration is not supported. You need to configure it yourself after the image is created.

2 Enabling Lite Server Resources

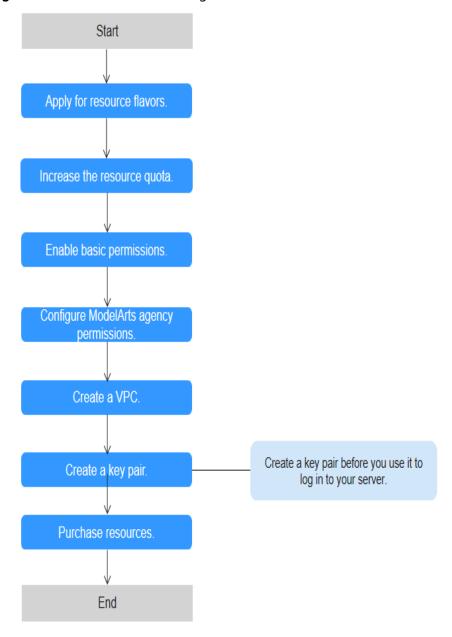


Figure 2-1 Flowchart for enabling resources

Table 2-1 Enabling resources

Phase	Step
Prerequisit es	1. Apply for resource specifications.
	2. Increase the resource quota.
	3. Enable basic permissions.
	4. Configure an agency authorization for ModelArts.
	5. Create a VPC.

Phase	Step
	6. (Optional) Create a key pair. (This step is not required if password login is used.)
Purchasing Lite Server resources	7. Purchase a resource pool on the ModelArts console.

Step 1: Applying for Resource Specifications

Contact Huawei Cloud customer manager to determine a resource solution for Lite Server. Apply for the required resource specifications. If there is no customer manager, submit a service ticket.

Step 2: Increasing Resource Quota

The resources required by the server may exceed the default resources (such as ECS, EIP, and SFS) provided by Huawei Cloud. In this case, you need to increase the resource quota.

- **Step 1** Log in to Huawei Cloud console.
- **Step 2** Hover over **Resources** from the top navigation bar and choose **My Quotas**.
- **Step 3** Click **Increase Quota** in the upper right corner, fill in the materials, and submit a service ticket.
 - □ NOTE

Increase the quota before purchasing and provisioning the resource, ensuring it exceeds the resource's requirements.

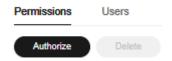
----End

Step 3: Enabling Basic Permissions

To enable basic permissions, log in to the management console as the administrator account and assign the basic permissions (such as ModelArts FullAccess, BMS FullAccess, ECS FullAccess, VPC FullAccess, VPC Administrator, and VPCEndpoint Administrator) required by server to IAM users.

- **Step 1** Log in to the IAM console.
- **Step 2** In the navigation pane on the left, choose **User Groups** and click **Create User Group** in the upper right corner.
- Step 3 Enter a group name and click OK.
- **Step 4** Click **Manage User** in the **Operation** column and add the target users.
- **Step 5** Click the user group name to go to the group details page.
- **Step 6** In the **Permissions** tab, click **Authorize**.

Figure 2-2 Assigning permissions



Step 7 Search for **ModelArts FullAccess** in the search box and select it.

Figure 2-3 ModelArts FullAccess



Use the same method to select BMS FullAccess, ECS FullAccess, VPC FullAccess, VPC Administrator, and VPCEndpoint Administrator. Server Administrator and DNS Administrator are dependent policies and are automatically selected.

- **Step 8** Click **Next** and set **Scope** to **All resources**.
- Step 9 Click OK.

----End

Step 4 Creating an Agency Authorization on ModelArts

Creating an agency

Create an agency in ModelArts to authorize access to other cloud services. To do so, log in to the ModelArts console. In the navigation pane on the left, choose **Permission Management**. On the displayed page, click **Add Authorization**.

- Updating an agency
 - Update the permissions for your existing ModelArts agency.
 - a. Log in to the ModelArts console. In the navigation pane on the left, choose AI Dedicated Resource Pools > Elastic Servers. On the displayed page, check whether a message is reported, indicating that the authorization is insufficient.

Figure 2-4 Insufficient permission on the elastic node server



b. Update the agency if needed. On the **Insufficient Permissions** page, set **Added To** to **Existing authorization** and click **OK**. The system shows the permission update is successful.

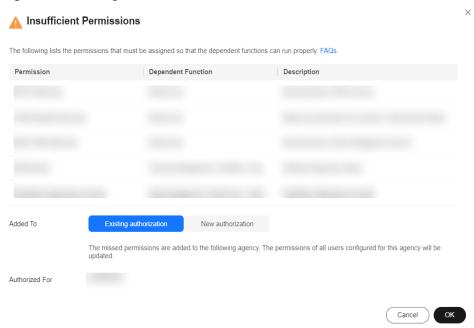


Figure 2-5 Adding authorization

Step 5: Creating a VPC

To create a VPC, you need to log in to the management console as the administrator.

- Step 1 Log in to the VPC console.
- **Step 2** Choose **Virtual Private Cloud > My VPCs**, click **Create VPC** in the upper right corner, and configure parameters to create a VPC.

For details about the parameters for creating a VPC, see **Creating a VPC and Subnet**.

----End

Step 6: Creating a Key Pair

□ NOTE

Key pairs are not required for password login.

- **Step 1** Log in to the ModelArts console.
- **Step 2** In the navigation pane on the left, choose **AI Dedicated Resource Pools** > **Elastic Servers**.
- Step 3 Click Buy Dedicated AI Server.
- **Step 4** Click **Create Key Pair**. Create a key pair and save it to a local path.

----End

Step 7: Purchasing Resources

Mapping Between Compute Resources and Image Versions lists the supported BMS images.

- **Step 1** Log in to the ModelArts console.
- Step 2 In the navigation pane on the left, choose AI Dedicated Resource Pools > Elastic Servers.
- **Step 3** Click **Buy Dedicated AI Server** and configure the parameters.

Table 2-2 Basic parameters

Parameter	Description
Resource Type	 BMS: A BMS features both the scalability of Elastic Cloud Servers (ECSs) and high performance of physical servers, providing dedicated servers on the cloud for you and your enterprise. ECS: ECS provides secure, scalable, on-demand compute
	resources, enabling you to flexibly deploy applications and workloads.
Billing Mode	Select Yearly/Monthly .
	Yearly/Monthly is a prepaid billing mode in which your subscription is billed based on the required duration. This mode is more cost-effective when the usage duration is predictable.
	Pay-per-use billing is not supported.
No.	Select a region near you to ensure the lowest latency possible. After the resources are purchased, you can switch the region in the upper left corner of the console to view the resources.
AZ	A standalone data center with an independent network and power supply. When deploying resources, consider your applications' requirements on disaster recovery (DR) and network latency.
	For high DR capability, deploy resources in different AZs within the same region.
	For lower network latency, deploy resources in the same AZ.
	If CloudPond is used, you can view the corresponding edge AZ. Edge AZs deploy cloud infrastructure and services at customer premises. In scenarios where there are high requirements on application access latency, local data retention, and local system interaction, edge AZs ensure easy deployment to the local environment. For details about CloudPond, see What Is CloudPond?

Table 2-3 Parameters for configuring a cluster

Parameter	Description
Server	Server name, which can contain 1 to 64 characters, including letters, digits, hyphens (-), and underscores (_). CAUTION The server name in the order will not be changed. If you change the name after placing the order, the new name will not be synchronized to the order.
CPU Architecture	CPU architecture of the resource type, which can be x86 or Arm . Select the CPU architecture based on the required flavors. If GPUs are used, select x86 . If NPUs are used, select Arm . The flavors vary by region. The actual flavors are displayed on the console. NOTE If no flavor is available on the page, contact Huawei Cloud technical support to apply for the flavor.
System Disk	This parameter is displayed only when you select a flavor that supports mounting. After an ECS is created, you can mount a data disk to the ECS or expand the capacity of the system disk on the ECS. The recommended value is not smaller than 100 GB.

Table 2-4 Parameters for configuring an image

Parameter	Description
Image	Public image A public image is a standard OS image provided by the system and is available to all users. It contains an OS and preinstalled public applications, such as the SDI iNIC driver, bmsnetwork-config (a network configuration program), and Cloud-Init (an initialization tool). If you need other applications or software, configure them on the new BMSs. ModelArts provides images, which support multiple OSs, built-in drivers and software for AI scenarios, and preset custom ModelArts OS optimization components. For details about supported images, see Mapping Between Compute Resources and Image Versions.
	Private image A private image is created from an external image file or a BMS and is available only to the user who created it. It contains an OS, preinstalled public applications, and the user's personal applications. You can select a private image to save your time from repeatedly configuring servers.

Table 2-5 Network parameters

Parameter	Description	
VPC	The VPC should be the same as that of other cloud services, such as MapReduce Service (MRS) and Cloud Container Engine (CCE) for network interaction.	
Subnet	Select a subnet of the current VPC.	
IPv6 Network	IPv6 is available when it is supported by the current subnet, flavors, and images.	
	Ensure that IPv6 has been enabled. For details about enabling IPv6, see Creating a Subnet for the VPC .	
	The requirements on flavors and images differ. Refer to the information displayed on the console.	
RoCE Network	When GPUs of series A are used, you need to configure the RoCE network to use the RoCE NICs on the hardware during distributed training.	
	This parameter is related to the selected flavors. RoCE network will not be available if any flavor does not support RoCE.	
	If RoCE is supported but has not been created, click Create RoCE .	
	If RoCE is supported and has been created, select an existing one. Repeated creation is not supported.	
Security Group	A security group is a collection of access control rules for ECSs that have the same security requirements and that are mutually trusted within a VPC.	

Table 2-6 Management parameters

Parameter	Description
Login Mode	Key pair is recommended because it features higher security than Password . If you select Password , ensure that the password meets complexity requirements to prevent malicious attacks.
	Key pair A key pair is used for BMS login authentication. You can select an existing key pair, or click Create Key Pair to create one.
	NOTE If you use an existing key pair, ensure that you have one.
	Password The initial password is used for authentication. You can log in to the BMS using the username and its initial password.
	If the BMS runs Linux, you can use username root and its initial password to log in to the BMS. If the BMS runs Windows, you can use username Administrator and its initial password to log in to the BMS. Password complexity must meet the following requirements:
	– Contains 8 to 26 characters.
	 Contains at least three types of the following characters: uppercase letters, lowercase letters, digits, and special characters (!@\$ %^=+ [{}]:, ./?).
	 The password should be different from the username or the username spelled backwards.
	 Cannot contain root, administrator, or their reverse.

Table 2-7 Advanced settings

Parameter	Description
Enterprise Project	This parameter is available only if you have enabled enterprise projects or your account is an enterprise account. You can contact your service manager to enable this function
	An enterprise project groups cloud resources, so you can manage resources and members by project. The default project is default .
	Select an enterprise project from the drop-down list. For details about enterprise projects, see <i>Enterprise Management User Guide</i> .
	CAUTION The enterprise project cannot be modified for a purchased server. Currently, the enterprise project information cannot be synchronized in the order.

Table 2-8 Purchase parameters

Parameter	Remarks
Quantity	You can purchase multiple instances simultaneously, with a value between 1 and 10 .
	Each instance generates a separate order, which must be paid for individually.

Step 4 Click **Next** to complete the instance creation. On the payment page that is displayed, pay for the resource order.

□ NOTE

Each instance generates a separate order, which must be paid for individually.

Step 5 After the payment, it takes about 20 to 60 minutes to create the server. After the server is created, the server status is **Running**.

□ NOTE

- If ModelArts fails to create an elastic server, there are multiple possible causes. The following provides several possibilities for quick troubleshooting.
 - Insufficient resources: Switch to the BMS page and check whether the specifications to be purchased are sold out. If so, there are no resources of this flavor. In this case, contact the customer manager to obtain resources and purchase again.
 - Insufficient quota: Check whether the resource quota of the account is sufficient. If
 the resource quota of the account, including the number of cores and RAM, is
 insufficient, the creation will fail. In this case, apply for a quota before purchasing
 the resource
 - Internal BMS error: Check whether there is an internal BMS error. If yes, submit a service ticket to BMS to locate and rectify the fault.
- If a container is used or shared by multiple users, you should restrict the container from accessing the OpenStack management address (169.254.169.254) to prevent host machine metadata acquisition. For details, see Forbidding Containers to Obtain Host Machine Metadata.

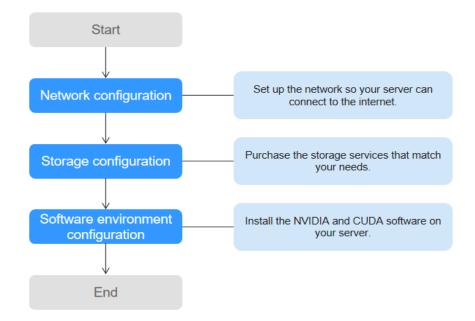
----End

3 Configuring Lite Server Resources

3.1 Configuration Process

After enabling Lite Server resources, you need to complete the configurations as follows.

Figure 3-1 Flowchart for configuring resources



Task Description Step 1 Configuring the Configure the network so that the Lite Server can **Network** communicate with the Internet. Before configuring the storage and software environment, ensure that the server can access the network. 2 Data disks need to be mounted to the server to Configuring the store data files. Currently, SFS, Object Storage Storage Service (OBS), and EVS are supported. 3 Configuring the The software to be pre-installed varies among **Software** images. View the installed software by referring **Environment** to Mapping Between Compute Resources and **Image Versions**. If the software pre-installed on the Lite Server cannot meet service requirements. you can configure the required software environment on the server.

Table 3-1 Resource configuration process

3.2 Configuring the Network

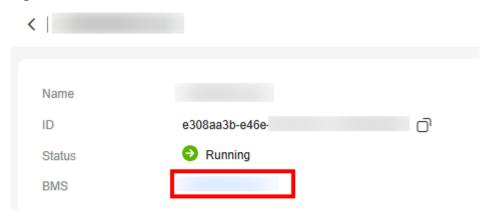
Configure the network so that Lite Server can communicate with the Internet. Network configuration involves the following two scenarios:

- **Binding an EIP to a Single Server**: Bind an EIP to a single server. The server exclusively uses network resources.
- Binding an EIP to Multiple Servers: An EIP is configured for a VPC. All servers in the VPC can access the Internet through the EIP and share network resources.

Binding an EIP to a Single Server

- **Step 1** Log in to the ModelArts management console.
- **Step 2** In the navigation pane on the left, choose **AI Dedicated Resource Pools** > **Elastic Servers**.
- **Step 3** Click the server name to go to the details page. On the displayed page, click the BMS name.

Figure 3-2 BMS

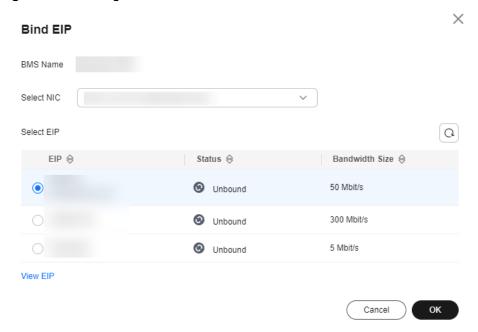


Step 4 Click the **EIPs** tab and then click **Bind EIP**.

The **Bind EIP** dialog box is displayed.

Select the EIP to be bound and click OK.

Figure 3-3 Binding an EIP



□ NOTE

Only one EIP can be bound to a NIC.

----End

Binding an EIP to Multiple Servers

□ NOTE

All servers must be deployed in the same VPC which does not have a NAT gateway or default route.

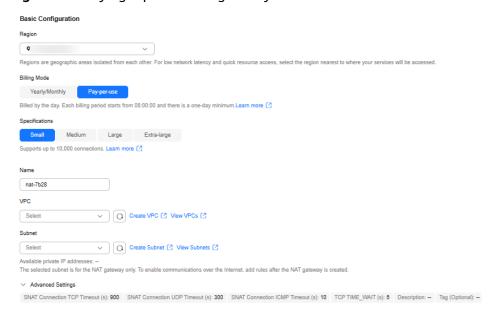
Step 1 Buy an EIP.

- 1. Log in to Huawei Cloud console.
- 2. In the service list on the left, choose **Networking** > **Elastic IP**.
- 3. Click Buy EIP.
- 4. Retain the default settings and click **Next**.
- 5. Confirm the configurations and select "I have read and agree to the *Elastic IP Service Statement*".
 - If you set Billing Mode to Pay-per-Use, click Submit.
 - If you set Billing Mode to Yearly/Monthly, click Pay Now.
 On the payment page, confirm the order information, and click Pay.

Step 2 Buy a public NAT gateway.

- 1. Log in to Huawei Cloud console.
- 2. In the service list on the left, choose **Network > NAT Gateway**.
- 3. Click Buy Public NAT Gateway.
- 4. Set **VPC**, **Subnet**, and **Billing Mode**. Retain the default settings for other parameters and click **Next**.

Figure 3-4 Buying a public NAT gateway



- 5. On the displayed page, confirm the information and click **Submit**.
 - If you set Billing Mode to Pay-per-Use, click Submit.
 - If you set Billing Mode to Yearly/Monthly, click Pay Now.
 On the payment page, confirm the order information, and click Pay.

□ NOTE

The VPC and subnet must be that of the server.

Step 3 Add an SNAT rule.

SNAT translates private IP addresses into EIPs, allowing servers in a VPC to share an EIP to access the Internet securely and efficiently.

- 1. On the **Public NAT Gateways** page, click the name of the created NAT gateway.
- 2. In the SNAT Rules tab, click Add SNAT Rule.
- 3. In the displayed dialog box, configure the SNAT rule as follows:
 - Scenario: Select VPC.
 - **Subnet**: Choose an existing subnet.
 - EIP: Select a created EIP.
- 4. Click OK.

Step 4 Configure a DNAT rule.

By adding a DNAT rule, the servers in a VPC can access services using SSH. For each server, a port corresponds to a DNAT rule, and one port can be mapped to only one EIP.

- 1. In the **DNAT Rules** tab, click **Add DNAT Rule**.
- 2. In the displayed dialog box, configure the DNAT rule as follows:
 - Scenario: Select VPC.
 - Port Type: Select Specific port.
 - Protocol: Select TCP.
 - **EIP**: Select a created EIP.
 - Outside Port: The recommended value ranges from 20000 to 30000.
 Ensure that the port number is unique.
 - Instance Type: Click Server and select a server.
 - NIC: Select a NIC.
 - Inside Port: Choose 22.
- 3. Click OK.

----End

3.3 Configuring the Storage

Currently, SFS, OBS, and EVS are supported for the server. The following table describes the differences of storage solutions. For details about how to configure local disks, see **Physical Machine Environment Configuration**.

Table 3-2 Comparison among SFS, OBS, and EVS

Dimensio n	SFS	OBS	EVS
Concept	SFS provides on- demand high- performance file storage, which can be shared by multiple cloud servers. SFS is similar to a remote directory for Windows or Linux OSs.	OBS provides massive, secure, reliable, and costeffective data storage for users to store data of any type and size.	EVS provides scalable block storage that features high reliability, high performance, and a variety of specifications for cloud servers to meet service requirements in different scenarios. An EVS disk is similar to a hard disk on a PC.
Data storage logic	SFS stores files and organizes them in a directory hierarchy.	OBS stores data as objects with metadata and unique identifiers. You can upload files directly to OBS. The system can generate metadata for files, or you can customize the metadata for files.	EVS stores binary data and cannot store files directly. To store files on an EVS disk, you need to format the file system first.
Access method	SFS file systems can be accessed only after being mounted to ECSs or BMSs through NFS or CIFS. You need to specify a network address or map it to a local directory for access.	Accessible through the Internet or Direct Connect (DC). You need to specify the bucket address for access and use transmission protocols such as HTTP and HTTPS.	EVS disks can be used and accessed from applications only after being attached to ECSs or BMSs and formatted.
Scenario	High-performance computing (HPC), media processing, file sharing, content management, and web services NOTE HPC: High bandwidth is required for shared file storage, such as gene sequencing and image rendering.	Big data analysis, static website hosting, online video on demand (VoD), gene sequencing, and intelligent video surveillance	HPC, enterprise core cluster applications, enterprise application systems, and development and testing NOTE HPC: High-speed and high-IOPS storage is required, such as industrial design and energy exploration.

Dimensio n	SFS	OBS	EVS
Capacity	РВ	ЕВ	ТВ
Latency	3–10 ms	10 ms	Sub-millisecond
IOPS/TPS	10,000 for a single file system	Tens of millions	128,000 for a single disk
Bandwidt h	GB/s	TB/s	MB/s
Data sharing	Yes	Yes	Yes
Remote access	Yes	Yes	No
Online editing	Yes	No	Yes
Used independe ntly	Yes	Yes	No (EVS must work with BMS to store files.)

Using SFS for Storage

Use SFS Turbo file system. SFS Turbo provides high-performance file storage on demand. It features high reliability and availability. It can be elastically expanded and performs better as its capacity grows. The service is suitable for a wide range of scenarios.

- **Step 1** Create a file system on the SFS console. For details, see **Creating an SFS Turbo File System**. File systems and ECSs in different AZs of the same region can communicate with each other. Therefore, ensure that SFS Turbo and the server are in the same region.
- **Step 2** Mount the file system to the server. For details, see **Mounting an NFS File System to ECSs (Linux)**.
- **Step 3** Set automatic mounting upon restart on the server to prevent mounting loss. For details, see **Mounting a File System Automatically**.

----End

Using OBS for Storage

Use the combination of parallel file systems and obsutil. The parallel file system provided by OBS is an optimized high-performance file semantic system with millisecond-level access latency, TB/s-level bandwidth, and million-level IOPS. You can use obsutil, a command line tool for accessing OBS, to perform configurations in OBS, for example, creating a bucket, uploading, downloading, and deleting files/folders. If you are familiar with command line interface (CLI), obsutil can provide you with better experience in batch processing and automated tasks.

- **Step 1** Create a parallel file system on the OBS console. For details, see **Creating a Parallel File System**.
- **Step 2** Download the corresponding obsutil to the BMS based on your OS and install it. For details, see **Downloading and Installing obsutil**.
- **Step 3** Configure the OBS endpoint and AK/SK for obsutil to interconnect with OBS. You can use obsutil to perform operations on OBS buckets and objects only after obtaining the OBS authentication. For details, see **Performing the Initial Configuration**.
- **Step 4** Use obsutil to upload and download OBS files in the BMS. For details about obsutil, see **obsutil Introduction**.

----End

Using EVS for Storage

Step 1 Purchase a disk on the EVS console, choose the AZ where the BMS is deployed, set **Attach to Server** to **Later**, choose a billing mode, and configure the disk size based on your needs. For details, see **Purchasing an EVS Disk**.

Figure 3-5 Buying a disk



Currently, an EVS disk cannot be mounted to the cloud server when it is being created. In this case, the system displays a message indicating that the Yearly/Monthly ECS has not been synchronized to the operations system. Please try again later. To address such problem, log in to the Huawei Cloud console, and choose **Billing** from the top menu bar. In the navigation pane on the left, choose **Orders** > **Renewals**. On the displayed page, check whether the ECS has been synchronized to the OS. If yes, set **Attach to Server** to **Later**.

Step 2 Go to the BMS details page of the server, click **Mount Disk**, and select the purchased EVS disk.

Figure 3-6 Mounting a disk



The mounted EVS disk will not be automatically deleted when you unsubscribe from a BMS. You can mount the disk to other BMSs or delete it as needed.

----End

3.4 Configuring the Software Environment

3.4.1 Configuring the Software Environment on the NPU Server

Precautions

This section describes how to configure the environment on an Snt9b BMS, including merging and mounting disks and installing Docker. Pay attention to the following before the configuration:

- During the first installation, once you have configured the basic information such as storage, firmware, driver, and network access, try not to make any changes.
- For developers who need to develop on a BMS, start an independent Docker container as your personal development environment. The Snt9b BMS contains eight-card compute resources, which can be used by multiple users for development and debugging. To avoid usage conflicts, cards should be arranged to each user beforehand, and users should develop in their own Docker containers.
- ModelArts provides standard base container images, in which the basic MindSpore/PyTorch framework and the development and debugging tool chain are preset. You can use the image directly. Alternatively, you can use your own service images or images provided by AscendHub. If the software version preset in the image does not meet your requirements, you can install and replace it.
- Use the exposed SSH port to connect to the container in remote development mode (VSCode SSH Remote or Xshell) for development. You can mount your storage directory to the container to store code and data.

NIOTE
 NOTE
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Most operations in this guide have been preset in the latest Snt9b BMS environment. No further configuration is required. Skip the step if it has been preset.

Physical Machine Environment Configuration

Step 1 Configure timeout parameters.

Log in to the server using SSH and check the timeout configuration.

echo \$TMOUT

If it is set to **300**, the server is disconnected after 5 minutes. You can configure the parameter to set a longer timeout interval. If it is set to **0**, skip this step. Run the following commands to configure the parameter:

```
vim /etc/profile
```

Change the value of **TMOUT** from **300** to **0** at the end of the file. The value **0** indicates that the idle connection is not disconnected. export TMOUT=0

Run the following command for the configuration to take effect on the current terminal:

TMOUT=0

By running the **export TMOUT=0** command, the idle timeout of the session is set to 0 during SSH connection to the Linux server, that is, the connection will not be automatically disconnected due to idleness. For security purposes, SSH connections may be automatically disconnected if no operation is performed for a while. However, if you are performing a task that requires long-time connection, run this command to prevent disconnection caused by idleness. You can run the **TMOUT=0** command in the current terminal session or add **export TMOUT=0** to the **/etc/profile** file. In this way, new sessions of all users will not be disconnected due to idleness.

Do not configure **TMOUT=0** in the production environment or on a public server, as it will bring certain security risks.

Step 2 Merge and mount disks.

After a BMS is purchased, there might be multiple unmounted nyme disks on the server. Before configuring the environment, you need to merge and mount the disks. This operation must be performed at the very first so that the content you stored will not be overwritten.

Run the **lsblk** command to check whether three 7-TB disks are not mounted.
 In the following figure, nvme0n1, nvme1n1, and nvme2n1 are not mounted.

Figure 3-7 Unmounted disks

```
[root@devserver-7354 ~]# lsblk
NAME
        MAJ:MIN RM
                     SIZE RO TYPE MOUNTPOINT
           8:0
                  0
                     150G
                            0 disk
sda
  -sda1
           8:1
                  0
                       1G
                            0 part /boot/efi
                  0
                     149G
                            0 part /
  sda2
           8:2
nvme0n1 259:0
                  0
                            0 disk
                       7T
nvme1n1 259:1
                  0
                            0 disk
                        7T
                  0
nvme2n1 259:2
                        7T
                            0 disk
[root@devserver-7354 ~]#
```

The MOUNTPOINT column indicates the directory where the disk is mounted, as shown in the following figure. You can skip this step and create a directory in /home.

Figure 3-8 Mounted disks

```
[root@devserver-7354 ~]# lsblk
NAME
                           MAJ:MIN RM
                                        SIZE RO TYPE MOUNTPOINT
sda
                                     0
                                        150G
                                              0 disk
                             8:0
  -sda1
                             8:1
                                     0
                                          1G
                                              0 part /boot/efi
 -sda2
                                     0
                                        149G
                                              0 part /
                             8:2
n∨me0n1
                           259:0
                                     0
                                          7T
                                              0 disk /home
nvme1n1
                           259:1
                                     0
                                          7T
                                              0 disk
  -nvme_group-docker_data 253:0
                                              0 lvm /docker
                                     0
                                         14T
                                     0
nvme2n1
                           259:2
                                          7T
                                              0 disk
                                     0
 -nvme_group-docker_data 253:0
                                              0 lvm
                                         14T
                                                      /docker
```

Run the automatic mounting script to mount /dev/nvme0n1 to /home for each developer to create their own home directory. Mount the other two disks to /docker for containers to use. If /docker does not have sufficient space, the root directory may be fully occupied when multiple container instances are created.

```
cd /root/tools/
sh create disk partitions.sh
```

After the configuration, run the **df** -h command to view the information about the mounted disks.

Figure 3-9 Viewing mounted disks

```
[root@devserver-modelarts home]#
Filesystem
                                                      Avail
                                                             Use% Mounted on
                                          Size
                                                 Used
devtmpfs
                                          756G
                                                    0
                                                        756G
                                                                0% /dev
tmpfs
                                                        756G
                                                                0% /dev/shm
                                          756G
                                                    0
                                          756G
tmpfs
                                                        756G
                                                  28M
                                                                1% /run
                                                        756G
                                                                0%
                                                                   /sys/fs/cgroup
/dev/sda2
                                          196G
                                                        185G
                                                                2% /
                                                 2.4G
                                                                1% /tmp
1% /boot/efi
tmpfs
/dev/sda1
                                          756G
                                                  40K
                                                        756G
                                         1022M
                                                 8.3M
                                                       1014M
/dev/mapper/nvme_group-docker_data
                                          14T
                                                 121G
                                                        14T
                                                                1% /docker
                                                  50G
                                                        7.0T
/dev/nvme0n1
                                          7.0T
                                                                1% /home
```

After the disks are merged and mounted, you can create a working directory and name it in /home.

Step 3 (Optional) Install the firmware and driver.

1. Run the **npu-smi info** command to check if the npu-smi tool can be used properly. If the following information is displayed, the npu-smi tool can be used properly.

If the command output is not complete as shown in the figure below (for example, an error is reported or only the upper part of the command output is displayed without the following process information), restore the npu-smi tool and install the firmware and driver of the new version. To do so, submit a service ticket to **contact Huawei Cloud technical support**.

oot@devserver-bms-fd775372-833351 ~]# npu-smi info npu-smi 23.0.rc3 Version: 23.0.rc3 NPU Chip Health Bus-Id Power(W) AICore(%) Temp(C) Memory-Usage(MB) Name 910B2 OK 0000:C1:00.0 0 / 0 4152 / 65536 / 0 910B2 OK 0000:01:00.0 0 / 0 4152 / 65536 / 0 910B2 94.5 0 OK 0000:C2:00.0 0 / 0 4152 / 65536 / 0 910B2 92.9 Θ 51 0 0 / 0 4152 / 6553<u>6</u> OK 0000:02:00.0 910B2 OK 0000:81:00.0 4 0 91.9 0 0 / 0 4152 / 65536 / Θ 910B2 5 0 OK 0000:41:00.0 0 / 0 4153 / 65536 / 0 910B2 OK 0000:82:00.0 92.2 0 0 / 0 4153 / 65536 / 0 910B2 OK 0000:42:00.0 0 / 0 4153 / 65536 / 0 Chip Process id Process name | Process memory(MB) No running processes found in NPU 0 No running processes found in NPU 1 No running processes found in NPU 2 No running processes found in NPU 3 No running processes found in NPU 4 No running processes found in NPU 5 No running processes found in NPU 6 esses found in NPU 7

Figure 3-10 Checking the npu-smi tool

2. View the environment information. Run the following command to view the current firmware and driver versions:

npu-smi info -t board -i 1 | egrep -i "software|firmware"

Figure 3-11 Viewing the firmware and driver versions

firmware indicates the firmware version, and **software** indicates the driver version.

If the current versions do not meet your requirements and need to be changed, see the subsequent operations.

3. View the OS version, check whether the architecture is AArch64 or x86_64, and obtain the firmware and driver packages from the Ascend official website. The firmware package is **Ascend-hdk-***Model-***npu-firmware_***Version.***run** and the driver package is **Ascend-hdk-***Model-***npu-driver_***Version_***linux- aarch64.run**. Only Huawei engineers and channel users have the permission to download the commercial version. For details, see **the download link**.

arch
cat /etc/os-release

Figure 3-12 Viewing the OS version and architecture

```
[root@localhost ~]# arch
aarch64
[root@localhost ~]# cat /etc/os-release
NAME="EulerOS"
VERSION="2.0 (SP10)"
ID="euleros"
VERSION_ID="2.0"
PRETTY_NAME="EulerOS 2.0 (SP10)"
ANSI_COLOR="0;31"
```

The following uses the packages that adapt to EulerOS 2.0 (SP10) and AArch64 as an example.

4. Install the firmware and driver packages.

□ NOTE

- 1. Installation sequence is vital.
 - 1. Initial installation: In scenarios where no driver is installed on a hardware device before delivery, or the installed driver and firmware on the hardware device have been uninstalled, you need to install the driver and then firmware.
 - 2. Overwrite installation: In scenarios where the driver and firmware have been installed on a hardware device and you need to install them again, install the firmware first and then the driver.

Generally, the firmware and driver are pre-installed on the Snt9b server before delivery. So in this case, **overwrite installation** is used as an example.

- a. If the firmware and driver to be installed are of a lower version, ensure that npu-smi functions, and install the packages without the need to uninstall the existing versions.
- b. If the firmware and driver fail to be installed, search for the solution in Developer Community based on the error message.

The installation commands are as follows.

a. Install the firmware and then restart the server.

```
chmod 700 *.run

# Actual package name
./Ascend-hdk-Model-npu-firmware_Version.run --full
reboot
```

b. Install the driver and enter **y** as prompted. You do not need to restart the server.

```
# Actual package name
./Ascend-hdk-Model-npu-driver_Version_linux-aarch64.run --full --install-for-all
```

After the installation, check the firmware and driver versions. If the output is normal, the installation is successful.

npu-smi info -t board -i 1 | egrep -i "software|firmware"

Figure 3-13 Checking the firmware and driver versions

```
[root@devserver-com ~]# npu-smi info -t board -i 1 | egrep -i "software|firmware"
Software Version : 23.0.rc3
Firmware Version : 6.4.0.4.220
```

Step 4 Install the Docker environment.

1. Run the **docker -v** command to check whether Docker has been installed. If yes, skip this step.

Run the following command to install Docker:

yum install -y docker-engine.aarch64 docker-engine-selinux.noarch docker-runc.aarch64

Run the docker -v command to check whether the installation is successful.

Figure 3-14 Viewing the Docker version

[root@localhost ~]# docker -v Docker version 18.09.0, build ba6df24

2. Configure IP forwarding for network access in containers.

Run the following command to check the value of **net.ipv4.ip_forward**. Skip this step if the value is **1**.

sysctl -p | grep net.ipv4.ip_forward

If the value is not **1**, run the following command to configure IP forwarding: sed -i 's/net\.ipv4\.ip_forward=0/net\.ipv4\.ip_forward=1/g' /etc/sysctl.conf sysctl -p | grep net.ipv4.ip_forward

3. Check whether Ascend-docker-runtime has been installed and configured in the environment.

docker info larep Runtime

If the runtime is **ascend** in the output, the installation and configuration are complete. In this case, skip this step.

Figure 3-15 Querying Ascend-docker-runtime

```
[root@devserver-modelarts-demanager-0eaabe8f ~]# docker info |grep Runtime
Runtimes: ascend runc
Default Runtime: ascend
```

If Ascend-docker-runtime is not installed, click **here** to install it. The software package is a Docker plug-in provided by Ascend. During Docker runtime, paths of Ascend drivers can be automatically mounted to the container. You do not need to specify **--device** during container startup. After the package is downloaded, upload it to the server and install it.

chmod 700 *.run

./Ascend-hdk-*Model*-npu-driver_*Version*_linux-aarch64.run --install

For details, see **Ascend Docker Runtime User Guide**.

4. Set the newly mounted disk as the path used by Docker containers.

Edit the **/etc/docker/daemon.json** file. If the file does not exist, create it. vim /etc/docker/daemon.json

Add the two configurations as shown in the following figure. To ensure that the JSON format is correct, add a comma (,) at the end of the **insecure-registries** line. **data_root** indicates the path where the Docker data is stored. **default-shm-size** indicates the default sharing size during container startup. The default value is **64 MB**. You can modify it in case the training fails due to insufficient sharing memory during distributed training.

Figure 3-16 Docker configuration

Save the configuration and run the following command to restart Docker for the configuration to take effect:

systemctl daemon-reload && systemctl restart docker

Step 5 (Optional) Install pip.

1. Check whether pip has been installed and whether the access to the pip source is normal. If yes, skip this step.

pip install numpy

2. If pip is not installed, run the following commands:

python -m ensurepip --upgrade ln -s /usr/bin/pip3 /usr/bin/pip

3. Configure the pip source.

mkdir -p ~/.pip vim ~/.pip/pip.conf

Add the following information to the ~/.pip/pip.conf file:

[global]
index-url = http://mirrors.myhuaweicloud.com/pypi/web/simple
format = columns
[install]
trusted-host=mirrors.myhuaweicloud.com

Step 6 Test the RoCE network.

Install CANN Toolkit.

Check whether CANN Toolkit has been installed on the server. If the version number is displayed, it has been installed.

cat /usr/local/Ascend/ascend-toolkit/latest/aarch64-linux/ascend_toolkit_install.info

If it is not installed, obtain the software package from the official website. For common users, **download the community edition**. For Huawei engineers and channel users, **download the commercial edition**.

Install CANN Toolkit. Replace the package name.

chmod 700 *.run

./Ascend-cann-toolkit_6.3.RC2_linux-aarch64.run --full --install-for-all

2. Install mpich-3.2.1.tar.gz.

Click **here** to download the package and run the following commands to install it:

```
mkdir -p /home/mpich
mv /root/mpich-3.2.1.tar.gz /home/
cd /home/;tar -zxvf mpich-3.2.1.tar.gz
cd /home/mpich-3.2.1
./configure --prefix=/home/mpich --disable-fortran
make && make install
```

3. Set environment variables and compile the HCCL operator.

```
export PATH=/home/mpich/bin:$PATH
cd /usr/local/Ascend/ascend-toolkit/latest/tools/hccl_test
export LD_LIBRARY_PATH=/home/mpich/lib/:/usr/local/Ascend/ascend-toolkit/latest/
lib64:$LD_LIBRARY_PATH
make MPI HOME=/home/mpich ASCEND DIR=/usr/local/Ascend/ascend-toolkit/latest
```

After the operator is compiled, the following information is displayed.

Figure 3-17 Compiled operator

```
[root@devserver-com hccl_test]# make MPI_HOME=/home/mpich ASCEND_DIR=/usr/local/Ascend/ascend-toolkit/latest
g++ -std=c++11 -Werror -fstack-protector-strong -fPIE -pie -02 -s -Wl,-z,relro
-Wl,-z,now -Wl,-z,noexecstack -Wl,--copy-dt-needed-entries ./common/src/hccl_check_buf_init.cc ./common/src/hccl_check_common.cc ./common/src/hccl_opbase_root
info_base.cc ./common/src/hccl_test_common.cc ./common/src/hccl_test_main.cc ./
opbase_test/hccl_allgather_rootinfo_test.cc -I./common/src -I/usr/local/Ascend/
ascend-toolkit/latest/include -I/usr/local/Ascend/ascend-toolkit/latest/include
-I/home/mpich/include -I./opbase_test -o all_gather_test -L/usr/local/Ascend/a
scend-toolkit/latest/lib64 -lhccl -L/usr/local/Ascend/ascend-toolkit/latest/lib
64 -lascendcl -L/home/mpich/lib -lmpi
all_gather_test compile completed
g++ -std=c++11 -Werror -fstack-protector-strong -fPIE -pie -02 -s -Wl,-z,relro
-Wl,-z,now -Wl,-z,noexecstack -Wl,--copy-dt-needed-entries ./common/src/hccl_check_buf_init.cc ./common/src/hccl_check_common.cc ./common/src/hccl_check_buf_init.cc ./common/src/hccl_test_common.cc ./common/src/hccl_test_main.cc ./
opbase_test/hccl_allreduce_rootinfo_test.cc -I./common/src -I/usr/local/Ascend/
ascend-toolkit/latest/lib64 -lhccl -L/usr/local/Ascend/ascend-toolkit/latest/lib64 -lhccl -L/usr/local/Ascend/ascend-toolk
```

Perform all_reduce_test in the single-node scenario.

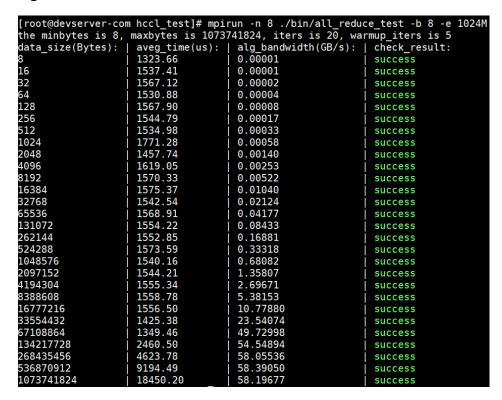
Go to the hccl test directory.

cd /usr/local/Ascend/ascend-toolkit/latest/tools/hccl_test

For single-node single-card, run the following command: mpirun -n 1 ./bin/all reduce test -b 8 -e 1024M -f 2 -p 8

For single-node multi-card, run the following command: mpirun -n 8 ./bin/all_reduce_test -b 8 -e 1024M -f 2 -p 8

Figure 3-18 all_reduce_test



- 5. Test the bandwidth of multi-node RoCE NICs.
 - a. Check the Ascend RoCE IP address. cat /etc/hccn.conf

Figure 3-19 Viewing Ascend RoCE IP address

```
[root@devserver-com hccl test]# cat /etc/hccn.conf
address_0=29.89.132.13
netmask 0=255.255.0.0
netdetect 0=29.89.0.1
gateway 0=29.89.0.1
send_arp_status_0=1
address_1=29.89.20.64
netmask 1=255.255.0.0
netdetect_1=29.89.0.1
gateway 1=29.89.0.1
send arp status 1=1
address 2=29.89.155.174
netmask_2=255.255.0.0
netdetect 2=29.89.0.1
gateway 2=29.89.0.1
send arp status 2=1
address_3=29.89.148.38
netmask 3=255.255.0.0
netdetect 3=29.89.0.1
gateway_3=29.89.0.1
send arp status 3=1
address 4=29.89.134.236
netmask 4=255.255.0.0
netdetect 4=29.89.0.1
gateway_4=29.89.0.1
send arp status 4=1
address 5=29.89.133.119
netmask 5=255.255.0.0
netdetect_5=29.89.0.1
gateway 5=29.89.0.1
send arp status 5=1
address 6=29.89.51.253
netmask 6=255.255.0.0
netdetect 6=29.89.0.1
gateway 6=29.89.0.1
send arp status 6=1
address_7=29.89.96.167
netmask 7=255.255.0.0
netdetect 7=29.89.0.1
gateway 7=29.89.0.1
```

b. Perform the RoCE test.

In session 1, run the -i Card ID command on the receive end.

```
hccn_tool -i 7 -roce_test reset
hccn_tool -i 7 -roce_test ib_send_bw -s 4096000 -n 1000 -tcp
```

In session 2, run the -iCard ID command on the sending end. The IP address of the receive end is at the end.

```
cd /usr/local/Ascend/ascend-toolkit/latest/tools/hccl_test
hccn tool -i 0 -roce test reset
hccn_tool -i 0 -roce_test ib_send_bw -s 4096000 -n 1000 address 192.168.100.18 -tcp
```

The following figure shows the RoCE test result.

Figure 3-20 RoCE test result (receive end)

```
[root@devserver-com hccl_test]# hccn_tool -i 7 -roce_test ib_send_bw -s 4096000 -n 1000 -tcp
Dsmi get perftest status end. (status=1)
Dsmi start roce perftest end. (out=1)
Dsmi get perftest status end. (status=2)
 DSMI get perftest status end. (status=2)
DSMi get perftest status end. (status=2)
DSMi get perftest status end. (status=2)
DSMi get perftest status end. (status=2)
DSMi get perftest status end. (status=1)
roce_report:
       Send BW Test
OFF
                                                                                                          Device
     Dual-port
     Number of qps
Connection type
                                                                                                         Transport type
Using SRQ
                                                                                                                                                          : IB
: OFF
    RX depth
CQ Moderation
                                                               100
4096[B]
Ethernet
    Mtu
Link type
GID index
     Max inline data : 0[B]
     rdma_cm QPs : OFF
Data ex. method : Ethernet
     local address: LID 0000 QPN 0x000a PSN 0xf97ccb
GID: 00:00:00:00:00:00:00:00:00:255:255:29:89:96:167
remote address: LID 0000 QPN 0x001a PSN 0x3a835e
     GID: 00:00:00:00:00:00:00:00:00:255:255:29:89:132:13
                                                                                                                                                                                                                           MsgRate[Mpps]
0.005989
                                        #iterations
1000
                                                                                                                                                       BW average[MB/sec]
23395.00
      #bytes
                                                                                          BW peak[MB/sec]
     4096000
                                                                                                0.00
```

Figure 3-21 RoCE test result (server)

```
twdevserver-com hccl_test]# |
get perftest status end. (st
start roce perftest end. (ou
get perftest status end. (st
_report:
                                                                    -i 0 -roce test ib send bw -s 4096000 -n 1000 address 29.89.96.167
                                               (status=1)
(out=1)
(status=1)
                          Send BW Test
: OFF
                                                  Device
Transport type
Using SRQ
                             4096[B]
Ethernet
Link type :
GID index :
Max inline data :
rdma_cm QPs :
Max inline data : 0[B]
rdma_cm QPs : 0FF
Data ex. method : Ethernet
#iterations
1000
                                          BW peak[MB/sec]
23372.40
                                                                         BW average[MB/sec] 23369.61
                                                                                                           MsgRate[Mpps]
0.005983
```

NOTE

If the RoCE bandwidth test has been started for a NIC, the following error message is displayed when the task is started again.

Figure 3-22 Error

```
[root@devserver-com hccl_test]# hccn_tool -i 7 -roce_test ib_send_bw -s 4096 -n
1000 -tcp
Dsmi get perftest status end. (status=2)
Roce perftest is doing, please try later.
Cmd execute failed!
```

Run the following command to stop the **roce_test** task and then start the task:

hccn_tool -i 7 -roce_test reset

- Run the following command to query the NIC status: for i in {0..7};do hccn_tool -i \${i} -link -g;done
- Run the following command to check the IP address connectivity of the NIC on a single node: for i in \$(seq 0 7);do hccn_tool -i \$i -net_health -g;done

----End

Creating a Containerized Custom Debugging Environment

Step 1 Prepare a service base image.

You could start your Docker container on the physical machine (PM) for development. You can use your service images or base images provided by ModelArts, including Ascend+PyTorch and Ascend+MindSpore.

- Choose an image based on your environment.
 # Container image matching Snt9b. The following shows an example.
 docker pull swr.
 region-code>.myhuaweicloud.com/atelier/<image-name>:<image-tag>
- 2. Start the container image. If multiple users and containers are sharing a machine, allocate the cards beforehand. Do not use cards occupied by other containers.

Start the container. Specify the container name and image information. **ASCEND_VISIBLE_DEVICES** indicates the cards to be used by the container, for example, **0-1,3** indicates cards 0, 1, and 3 are used. The hyphens (-) specify the range.

-v /home:/home_host indicates mounting the home directory of the host to the **home_host** directory of the container. Use this mounting directory in the container to store code and data for persistent storage.

docker run -itd --cap-add=SYS_PTRACE -e ASCEND_VISIBLE_DEVICES=0 -v /home:/home_host -p

docker run -itd --cap-add=SYS_PTRACE -e ASCEND_VISIBLE_DEVICES=0 -v /home:/home_host -p 51234:22 -u=0 --name *Custom container name SWR address of the image pulled in the preceding step* /bin/bash

Access the container.

docker exec -ti Custom container name in the last command bash

4. Access the Conda environment.

source /home/ma-user/.bashrc

5. View the information of available cards in the container.

If the following error message is displayed, the card specified by **ASCEND_VISIBLE_DEVICES** during container startup is occupied by another container. In this case, select another card and restart the new container.

Figure 3-23 Error

```
(PyTorch-1.11.0) [root@8e2a7f7f9f7a ma-user]# npu-smi info
DrvMngGetConsoleLogLevel failed. (g_conLogLevel=3)
dcmi model initialized failed, because the device is used. ret is -8020
```

- 6. After you run the **npu-smi info** command and the output is normal, run the following commands to test the container environment. If the output is normal, the container environment is available.
 - PyTorch image test: python3 -c "import torch;import torch_npu; a = torch.randn(3, 4).npu(); print(a + a);"
 - MindSpore image test:

 # The run_check program of MindSpore does not adapt to Snt9b. Configure two environment variables first.

 unset MS_GE_TRAIN

 unset MS_ENABLE_GE

 python -c "import

 mindspore;mindspore.set_context(device_target='Ascend');mindspore.run_check()"

 # Restore the environment variables after the test for actual training.

 export MS_GE_TRAIN=1

 export MS_ENABLE_GE=1

Figure 3-24 Accessing the Conda environment and performing a test

Step 2 (Optional) Configure SSH access for the container.

If you need to use the VS Code or SSH tool to directly connect to the container for development, perform the following operations:

1. After accessing the container, run the SSH startup command to start the SSH service.

```
ssh-keygen -A
/usr/sbin/sshd
# Check whether SSH is started.
ps -ef |grep ssh
```

Set a password for the **root** user as prompted. passwd

Figure 3-25 Setting a password for user root

```
[root@9f4f3b6794f7 ~]$ passwd
Changing password for user root.
New password:
Retype new password:
passwd: all authentication tokens updated successfully.
```

Run the exit command to exit the container and perform the SSH test on the host.

ssh root@Host IP address -p 51234 (Mapped port number)

Figure 3-26 Perform the SSH test.

```
[root@localhost home]# ssh root@90.90.3.71 -p 51234 root@90.90.3.71's password:
Authorized users only. All activities may be monitored and reported.
```

If the error message "Host key verification failed" is displayed when you perform the SSH container test on the host machine, delete the **~/.ssh/known_host** file from the host machine and try again.

4. Use VS Code SSH to connect to the container environment.

If you have not used VS Code SSH, install the VS Code environment and Remote-SSH plug-in by referring to **Step1 Manually Connecting to a Notebook Instance Through VS Code**.

Open VSCode Terminal and run the following command to generate a key pair on the local computer. If you already have a key pair, skip this step. ssh-keygen -t rsa

Add the public key to the authorization file of the remote server. Replace the server IP address and container port number.

cat ~/.ssh/id_rsa.pub | ssh root@*Server IP address* -p *Container port number* "mkdir -p ~/.ssh && cat >> ~/.ssh/authorized_keys"

Open the Remote-SSH configuration file of VSCode and add SSH configuration items. Replace the server IP address and container port number.

HostName Server IP address
User root
port SSH port number of the container
identityFile ~\.ssh\id_rsa
StrictHostKeyChecking no
UserKnownHostsFile /dev/null
ForwardAgent yes

Note: Use the key to log in. If you want to use the password, delete the identityFile configuration and enter the password as prompted during the connection.

After the connection, install the Python plug-in. For details, see **Install the Python Plug-in in the Cloud Development Environment**.

Step 3 (Optional) Install CANN Toolkit.

CANN Toolkit has been installed in the preset images provided by ModelArts. If you need to use another version or use your own image that is not preset with CANN Toolkit, see the following operations.

- 1. Check whether CANN Toolkit has been installed in the container. If the version number is displayed, it has been installed.

 cat /usr/local/Ascend/ascend-toolkit/latest/aarch64-linux/ascend toolkit install.info
- If it is not installed or needs to be upgraded, obtain the software package from the official website. For common users, download the community edition. For Huawei engineers and channel users, download the commercial edition.

```
Install CANN Toolkit. Replace the package name.
chmod 700 *.run
./Ascend-cann-toolkit_6.3.RC2_linux-aarch64.run --full --install-for-all
```

3. If it has been installed but needs to be upgraded, run the following command. Replace the package name.

```
chmod 700 *.run
./Ascend-cann-toolkit_6.3.RC2_linux-aarch64.run --upgrade --install-for-all
```

Step 4 (Optional) Install MindSpore Lite.

MindSpore Lite has been installed in the preset image. If you need to use another version or use your own image that is not preset with MindSpore Lite, see the following operations.

- 1. Check whether MindSpore Lite has been installed in the container. If the software information and version are displayed, it has been installed. pip show mindspore-lite
- 2. If it is not installed, download the .whl and .tar.gz packages from the official website and download them. Replace the package names. pip install mindspore_lite-2.1.0-cp37-cp37m-linux_aarch64.whl mkdir -p /usr/local/mindspore-lite tar -zxvf mindspore-lite-2.1.0-linux-aarch64.tar.gz -C /usr/local/mindspore-lite --strip-components 1

Step 5 Configure the pip source.

The pip source has been configured in the preset image provided by ModelArts. To use your own service images, configure it by referring to **Step 5**.

Step 6 Configure a Yum repository.

Configure a Yum repository on Huawei EulerOS.

```
# Create the EulerOS.repo file in the /etc/yum.repos.d/ directory,
cd /etc/yum.repos.d/
mv EulerOS.repo EulerOS.repo.bak
vim EulerOS.repo
# Configure the EulerOS.repo file based on the EulerOS version and system architecture. EulerOS 2.10 is
used as an example.
[base]
name=EulerOS-2.0SP10 base
baseurl=https://mirrors.huaweicloud.com/euler/2.10/os/aarch64/
enabled=1
gpgcheck=1
gpgkey=https://mirrors.huaweicloud.com/euler/2.10/os/RPM-GPG-KEY-EulerOS
# Clear the existing Yum cache.
yum clean all
# Generate a new Yum cache.
yum makecache
# Perform a test.
yum update --allowerasing --skip-broken --nobest
```

Configure a Yum repository in HCE OS.

```
# Download the new hce.repo file to the /etc/yum.repos.d/ directory.
wget -O /etc/yum.repos.d/hce.repo https://mirrors.huaweicloud.com/artifactory/os-conf/hce/hce.repo
# Clear the existing Yum cache.
yum clean all
# Generate a new Yum cache.
yum makecache
# Perform a test.
yum update --allowerasing --skip-broken --nobest
```

Step 7 To use **git clone** and **git lfs** commands to download large models, see the following operations:

1. The Euler source does not have the git-lfs package. Therefore, you need to decompress the package. To do so, enter the following address in the address box of the browser, download the git-lfs package, and upload it to the /home directory on the server. This directory is mounted to the /home_host directory of the container when the container is started. In this way, the git-lfs package can be directly used in the container.

https://github.com/git-lfs/qit-lfs/releases/download/v3.2.0/git-lfs-linux-arm64-v3.2.0.tar.gz

2. Go to the container and run the **git-lfs** installation commands.

```
cd /home_host
tar -zxvf git-lfs-linux-arm64-v3.2.0.tar.gz
cd git-lfs-3.2.0
sh install.sh
```

- 3. Disable SSL verification for Git configuration. git config --global http.sslVerify false
- 4. The following commands use code in diffusers as an example. Replace the development directory.

```
# git clone diffusers source code, -b You can specify a branch for this parameter. Replace the development directory.

cd /home_host/User directory
mkdir sd
cd sd
git clone https://github.com/huggingface/diffusers.git -b v0.11.1-patch
```

Run the **git clone** command to download the model on Hugging Face. The following uses a stable-diffusion (SD) model as an example. If the **SSL_ERROR_SYSCALL** error is reported during the download, try again. The download may take several hours due to network restrictions and large file size. If the download still fails after multiple retries, download the large file from the website and upload it to the personal development directory in / **home** on the server. To skip the large files during download, set **GIT_LFS_SKIP_SMUDGE** to **1**.

```
git lfs install
git clone https://huggingface.co/runwayml/stable-diffusion-v1-5 -b onnx
```

Figure 3-27 Downloaded code

```
[root@38a757e4636a sd]# git clone <a href="https://github.com/huggingface/diffusers.git">https://github.com/huggingface/diffusers.git</a> -b v0.11.1-patch cloning into 'diffusers'...
remote: Enumerating objects: 34118, done.
remote: Counting objects: 100% (10965/10965), done.
remote: Compressing objects: 100% (765/765), done.
remote: Total 34118 (delta 10639), reused 10273 (delta 10190), pack-reused 23153
Receiving objects: 100% (34118/34118), 21.44 MiB | 9.58 MiB/s, done.
Resolving deltas: 100% (25313/25313), done.
[root@38a757e4636a sd]# cd diffusers/
[root@38a757e4636a diffusers]# git branch
* v0.11.1-patch
[root@38a757e4636a diffusers]#
```

Step 8 Save the image in the container environment.

After the environment is configured, you can develop and debug the service code. To prevent the environment from being lost after the host is restarted, run the following commands to save the configured environment as a new image:

```
# Check the ID of the container to be saved as an image.

docker ps
# Save the image.

docker commit Container ID Custom image name.Custom image tag
# View the saved image.

docker images
# If you need to share the image with others in other environments, save the image as a local file. This command takes a long time. You can view the file after it is saved.

docker save -o Custom name.tar Image name.Image tag
# Load the file on other hosts. After the file is loaded, you can view the image.

docker load --input Custom name.tar
```

For details about how to migrate services to Ascend for development and debugging, see the related documents.

----End

3.4.2 Configuring the Software Environment on the GPU Server

Scenario

This section describes how to configure the environment on a GPU BMS, including installing NVIDIA and CUDA drivers. For different GPU preset images, the pre-installed software varies. You can view the installed software by referring to Mapping Between Compute Resources and Image Versions. The following describes the common software installation procedure. You can view the content based on the software to be installed.

- Installing a NVIDIA Driver
- Installing a CUDA Toolkit
- Installing Docker
- Installing nvidia-fabricmanager

The following are the typical configuration scenarios. View the related documents for quick configuration.

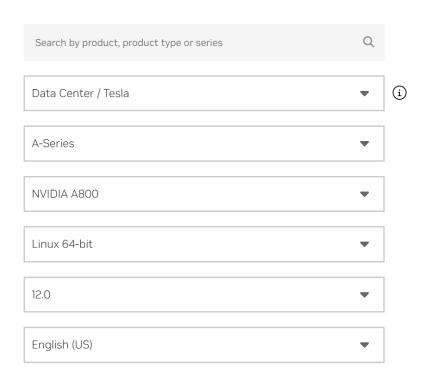
- Installing NVIDIA 515 and CUDA 11.7 on a GP Vnt1 BMS in EulerOS 2.9
- Installing NVIDIA 470 and CUDA 11.4 on a GP Vnt1 BMS in Ubuntu 18.04
- Installing NVIDIA 515 and CUDA 11.7 on a GP Vnt1 BMS in Ubuntu18.04
- Installing NVIDIA 515 and CUDA 11.7 on a GP Ant8 BMS in Ubuntu 20.04

Installing a NVIDIA Driver

- Step 1 Visit the NVIDIA official website.
- **Step 2** The Ant8 specifications are used as an example. Select a driver based on the Ant8 details and the required CUDA version.

Figure 3-28 Selecting a driver

Manual Driver Search



The driver version is automatically displayed and downloaded. wget https://cn.download.nvidia.com/tesla/470.182.03/NVIDIA-Linux-x86_64-470.182.03.run

Step 3 Assign permissions.

chmod +x NVIDIA-Linux-x86_64-470.182.03.run

Step 4 Run the installation file.

./NVIDIA-Linux-x86_64-470.182.03.run

The NVIDIA-DRIVER driver is installed.

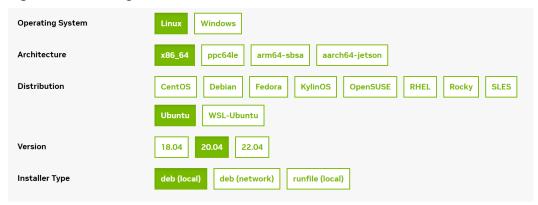
----End

Installing a CUDA Toolkit

The NVIDIA driver is installed based on CUDA 12.0. In this case, CUDA 12.0 is installed by default.

- Step 1 Visit CUDA Toolkit.
- **Step 2** After you set the OS, architecture, distribution, version, and installation type, an installation command is generated. Copy the command and run it.

Figure 3-29 Settings



The generated installation commands are as follows:

wget https://developer.download.nvidia.com/compute/cuda/repos/ubuntu2004/x86_64/cuda-ubuntu2004.pin sudo mv cuda-ubuntu2004.pin /etc/apt/preferences.d/cuda-repository-pin-600 wget https://developer.download.nvidia.com/compute/cuda/12.1.1/local_installers/cuda-repo-ubuntu2004-12-1-local_12.1.1-530.30.02-1_amd64.deb sudo dpkg -i cuda-repo-ubuntu2004-12-1-local_12.1.1-530.30.02-1_amd64.deb sudo cp /var/cuda-repo-ubuntu2004-12-1-local/cuda-*-keyring.gpg /usr/share/keyrings/ sudo apt-get update sudo apt-get -y install cuda

To obtain CUDA of earlier versions, see CUDA Toolkit Archive.

----End

Installing Docker

Docker is not installed in some preset images of Vnt1 BMS. To install Docker, see the following operations:

Step 1 Install Docker.

curl https://get.docker.com | sh && sudo systemctl --now enable docker

Step 2 Install the NIVDIA container plug-in.

distribution=\$(. /etc/os-release;echo \$ID\$VERSION_ID)
&& curl -fsSL https://nvidia.github.io/libnvidia-container/gpgkey | sudo gpg --dearmor -o /usr/share/
keyrings/nvidia-container-toolkit-keyring.gpg
&& curl -s -L https://nvidia.github.io/libnvidia-container/\$distribution/libnvidia-container.list |
sed 's#deb https://#deb [signed-by=/usr/share/keyrings/nvidia-container-toolkit-keyring.gpg] https://#g' |
sudo tee /etc/apt/sources.list.d/nvidia-container-toolkit.list
apt-get update
apt-get install -y nvidia-container-toolkit
nvidia-ctk runtime configure --runtime=docker
systemctl restart docker

Step 3 Check whether the Docker environment has been installed.

The following uses PyTorch 2.0 as an example. The image used in this case is large and it may take a while to pull the image.

docker run -ti --runtime=nvidia --gpus all pytorch/pytorch:2.0.0-cuda11.7-cudnn8-devel bash

Figure 3-30 Image pulled

----End

Installing nvidia-fabricmanager

NVLink and NVSwitch are supported for Ant GPUs. If you use a node with multiple GPUs, install nvidia-fabricmanager matching your driver version to enable interconnection between GPUs. Otherwise, GPU pods may fail to be used.

The nvidia-fabricmanager version must be the same as the nvidia driver version.

The following uses version 515.105.01 as an example.

```
version=515.105.01
main_version=$(echo $version | awk -F '.' '{print $1}')
apt-get update
apt-get -y install nvidia-fabricmanager-${main_version}=${version}-*
```

Verify the driver installation result. Start the fabricmanager service and check whether the status is **RUNNING**.

```
nvidia-smi -pm 1
nvidia-smi
systemctl enable nvidia-fabricmanager
systemctl start nvidia-fabricmanager
systemctl status nvidia-fabricmanager
```

Installing NVIDIA 515 and CUDA 11.7 on a GP Vnt1 BMS in EulerOS 2.9

This section describes how to install NVIDIA 515.105.01 and CUDA 11.7.1 on a GP Vnt1 BMS in EulerOS 2.9.

Step 1 Install the NVIDIA driver.

```
wget https://us.download.nvidia.com/tesla/515.105.01/NVIDIA-Linux-x86_64-515.105.01.run chmod 700 NVIDIA-Linux-x86_64-515.105.01.run

yum install -y elfutils-libelf-devel
./NVIDIA-Linux-x86_64-515.105.01.run --kernel-source-path=/usr/src/kernels/
4.18.0-147.5.1.6.h998.eulerosv2r9.x86_64
```

□ NOTE

By default, the Yum repository used by the Vnt1 BMS is http://repo.huaweicloud.com, which is available. If an error message is displayed when you run the **yum update** command, indicating that a software package conflict occurs, run the **yum remove** *xxx* **software package** command.

The NVIDIA driver is a binary file and requires the **libelf** library in the **elfutils-libelf-devel** development package in the system. It provides a set of C functions for reading, modifying, and creating ELF files. NVIDIA drivers need these functions to parse the currently running kernel and other related information.

During the installation, select **OK** or **YES** as prompted. After the installation, run the **reboot** command to restart the server. Log in to the server again and run the following command to view the GPU information:

nvidia-smi -pm 1 #This command will be executed for a while. Wait patiently. The persistent mode is enabled to optimize the GPU performance on the Linux instance.

Step 2 Install CUDA.

wget https://developer.download.nvidia.com/compute/cuda/11.7.1/local_installers/cuda_11.7.1_515.65.01_linux.run chmod 700 cuda_11.7.1_515.65.01_linux.run ./cuda_11.7.1_515.65.01_linux.run --toolkit --samples --silent

Check the installation result.

/usr/local/cuda/bin/nvcc -V

Step 3 Install PyTorch 2.0 and verify CUDA.

To install PyTorch 2.0, Python 3.10 is required, and the miniconda environment needs to be installed and configured.

1. Install miniconda and create the alpha environment.

wget https://repo.anaconda.com/miniconda/Miniconda3-py310_23.1.0-1-Linux-x86_64.sh chmod 750 Miniconda3-py310_23.1.0-1-Linux-x86_64.sh bash Miniconda3-py310_23.1.0-1-Linux-x86_64.sh -b -p /home/miniconda export PATH=/home/miniconda/bin:\$PATH conda create --quiet --yes -n alpha python=3.10

2. Install PyTorch 2.0 and verify the CUDA status.

Install PyTorch 2.0 in the alpha environment and use the Tsinghua PIP source. source activate alpha pip install torch==2.0 -i https://pypi.tuna.tsinghua.edu.cn/simple

Verify the installation status of PyTorch and CUDA. If the output is **True**, the installation is successful.

import torch
print(torch.cuda.is_available())

----End

Installing NVIDIA 470 and CUDA 11.4 on a GP Vnt1 BMS in Ubuntu 18.04

This section describes how to install NVIDIA 470 and CUDA 11.4 on a GP Vnt1 BMS in Ubuntu 18.04.

Step 1 Install the NVIDIA driver.

apt-get update sudo apt-get install nvidia-driver-470

Step 2 Install CUDA.

wget https://developer.download.nvidia.com/compute/cuda/11.4.4/local_installers/cuda_11.4.4_470.82.01_linux.run chmod +x cuda_11.4.4_470.82.01_linux.run -.toolkit --samples --silent

Step 3 Verify the NVIDIA installation result.

nvidia-smi -pm 1 nvidia-smi /usr/local/cuda/bin/nvcc -V

Step 4 Install PyTorch 2.0 and verify CUDA.

To install PyTorch 2.0, Python 3.10 is required, and the miniconda environment needs to be installed and configured.

1. Install miniconda and create the alpha environment.

wget https://repo.anaconda.com/miniconda/Miniconda3-py310_23.1.0-1-Linux-x86_64.sh chmod 750 Miniconda3-py310_23.1.0-1-Linux-x86_64.sh bash Miniconda3-py310_23.1.0-1-Linux-x86_64.sh -b -p /home/miniconda export PATH=/home/miniconda/bin:\$PATH conda create --quiet --yes -n alpha python=3.10

2. Install PyTorch 2.0 and verify the CUDA status.

Install PyTorch 2.0 in the alpha environment and use the Tsinghua PIP source. source activate alpha conda install pytorch torchvision torchaudio pytorch-cuda=11.7 -c pytorch -c nvidia python

Verify the installation status of PyTorch and CUDA. If the output is **True**, the installation is successful.

import torch
print(torch.cuda.is_available())

----End

Installing NVIDIA 515 and CUDA 11.7 on a GP Vnt1 BMS in Ubuntu18.04

This section describes how to install NVIDIA 515 and CUDA 11.7 on a GP Vnt1 BMS in Ubuntu18.04.

Step 1 Install the NVIDIA driver.

wget https://us.download.nvidia.com/tesla/515.105.01/NVIDIA-Linux-x86_64-515.105.01.run chmod +x NVIDIA-Linux-x86_64-515.105.01.run ./NVIDIA-Linux-x86_64-515.105.01.run

Step 2 Install CUDA.

wget https://developer.download.nvidia.com/compute/cuda/11.7.1/local_installers/cuda_11.7.1_515.65.01_linux.run chmod +x cuda_11.7.1_515.65.01_linux.run --toolkit --samples -silent

Step 3 Install Docker.

curl https://get.docker.com | sh && sudo systemctl --now enable docker

Step 4 Install the NIVDIA container plug-in.

distribution=\$(. /etc/os-release;echo \$ID\$VERSION_ID)
&& curl -fsSL https://nvidia.github.io/libnvidia-container/gpgkey | sudo gpg --dearmor -o /usr/share/
keyrings/nvidia-container-toolkit-keyring.gpg
&& curl -s -L https://nvidia.github.io/libnvidia-container/\$distribution/libnvidia-container.list |
sed 's#deb https://#deb [signed-by=/usr/share/keyrings/nvidia-container-toolkit-keyring.gpg] https://#g' |
sudo tee /etc/apt/sources.list.d/nvidia-container-toolkit.list
apt-get update
apt-get install -y nvidia-container-toolkit

nvidia-ctk runtime configure --runtime=docker systemctl restart docker

Step 5 Check whether the Docker environment has been installed.

The following uses PyTorch 2.0 as an example. The image used in this case is large and it may take a while to pull the image.

docker run -ti --runtime=nvidia --gpus all pytorch/pytorch:2.0.0-cuda11.7-cudnn8-devel bash

Figure 3-31 Image pulled

----End

Installing NVIDIA 515 and CUDA 11.7 on a GP Ant8 BMS in Ubuntu 20.04

This section describes how to install NVIDIA driver 515, CUDA 11.7, and nvidia-fabricmanager 515 on GP Ant8 BMS (Ubuntu 20.04) and perform the nccl-test test.

Step 1 Replace the APT source.

sudo sed -i "s@http://.*archive.ubuntu.com@http://repo.huaweicloud.com@g" /etc/apt/sources.list sudo sed -i "s@http://.*security.ubuntu.com@http://repo.huaweicloud.com@g" /etc/apt/sources.list sudo apt update

Step 2 Install the NVIDIA driver.

wget https://us.download.nvidia.com/tesla/515.105.01/NVIDIA-Linux-x86_64-515.105.01.run chmod +x NVIDIA-Linux-x86_64-515.105.01.run ./NVIDIA-Linux-x86_64-515.105.01.run

Step 3 Install CUDA.

Install the .run package.
wget https://developer.download.nvidia.com/compute/cuda/11.7.0/local_installers/
cuda_11.7.0_515.43.04_linux.run
chmod +x cuda_11.7.0_515.43.04_linux.run
./cuda_11.7.0_515.43.04_linux.run --toolkit --samples --silent

Step 4 Install NCCL.

□ NOTE

- For details about how to install NCCL, see NVIDIA Deep Learning NCCL Documentation.
- For details about the mapping between NCCL and CUDA versions and the installation method, see NCL Developer.

The following uses CUDA 11.7 as an example. Install NCCL.

```
wget https://developer.download.nvidia.com/compute/cuda/repos/ubuntu2004/x86_64/cuda-keyring_1.0-1_all.deb sudo dpkg -i cuda-keyring_1.0-1_all.deb sudo apt update sudo apt install libnccl2=2.14.3-1+cuda11.7 libnccl-dev=2.14.3-1+cuda11.7
```

The following is displayed after NCCL is installed.

Figure 3-32 Viewing NCCL

```
root@wangjianfeng:~# root@wangjianfeng:~# root@wangjianfeng:~# grep nccl i libnccl_lew 2.14.3-1+cuda11.7 amd64 NVIDIA Collective Communication Library (NCCL) Development Files ii libnccl_2 2.14.3-1+cuda11.7 amd64 NVIDIA Collective Communication Library (NCCL) Runtime root@wangjianfeng:~# root@wangjianfeng:~#
```

Step 5 Install nvidia-fabricmanager.

□ NOTE

The nvidia-fabricmanager version must be the same as the nvidia driver version.

```
version=515.105.01
main_version=$(echo $version | awk -F '.' '{print $1}')
apt-get update
apt-get -y install nvidia-fabricmanager-${main_version}=${version}-*
```

Verify the driver installation result. Start the fabricmanager service and check whether the status is **RUNNING**.

```
nvidia-smi -pm 1
nvidia-smi
systemctl enable nvidia-fabricmanager
systemctl start nvidia-fabricmanager
systemctl status nvidia-fabricmanager
```

Step 6 Install nv-peer-memory.

```
git clone https://github.com/Mellanox/nv_peer_memory.git
cd ./nv_peer_memory
./build_module.sh
cd /tmp
tar xzf /tmp/nvidia-peer-memory_1.3.orig.tar.gz
cd nvidia-peer-memory-1.3
dpkg-buildpackage -us -uc
dpkg -i ../nvidia-peer-memory-dkms_1.2-0_all.deb
```

nv_peer_mem works in Linux kernel mode. Run the **lsmod | grep peer** command to check whether nv_peer_mem is loaded to the kernel.

□ NOTE

• If the code cannot be pulled by running the git clone command, configure git.

git config --global core.compression -1 export GIT_SSL_NO_VERIFY=1 git config --global http.sslVerify false git config --global http.postBuffer 10524288000 git config --global http.lowSpeedLimit 1000 git config --global http.lowSpeedTime 1800

• If nv-peer-memory is not displayed after the installation, the InfiniBand driver version may be too early. In this case, upgrade InfiniBand.

wget https://content.mellanox.com/ofed/MLNX_OFED-5.4-3.6.8.1/MLNX_OFED_LINUX-5.4-3.6.8.1-ubuntu20.04-x86_64.tgz

tar -zxvf MLNX_OFED_LINUX-5.4-3.6.8.1-ubuntu20.04-x86_64.tgz cd MLNX_OFED_LINUX-5.4-3.6.8.1-ubuntu20.04-x86_64

apt-get install -y python3 gcc quilt build-essential bzip2 dh-python pkg-config dh-autoreconf python3-distutils debhelper make

./mlnxofedinstall --add-kernel-support

- For details about how to install a later version, see Linux InfiniBand Drivers. For example, install the latest version, which is MLNX_OFED-5.8-2.0.3.0. wget https://content.mellanox.com/ofed/MLNX_OFED-5.8-2.0.3.0/MLNX_OFED_LINUX-5.8-2.0.3.0-ubuntu20.04-x86_64.tgz tar -zxvf MLNX_OFED_LINUX-5.8-2.0.3.0-ubuntu20.04-x86_64.tgz cd MLNX_OFED_LINUX-5.8-2.0.3.0-ubuntu20.04-x86_64 apt-get install -y python3 gcc quilt build-essential bzip2 dh-python pkg-config dh-autoreconf python3-distutils debhelper make ./mlnxofedinstall --add-kernel-support
- After nv_peer_mem is installed, view its status. /etc/init.d/nv_peer_mem/ status

If the file does not exist, the file may not be copied by default during the installation. In this case, you need to copy the file.

cp /tmp/nvidia-peer-memory-1.3/nv_peer_mem.conf /etc/infiniband/

cp /tmp/nvidia-peer-memory-1.3/debian/tmp/etc/init.d/nv_peer_mem /etc/init.d/

Step 7 Configure environment variables.

□ NOTE

The MPI path version must match. You can run the **ls /usr/mpi/gcc/** command to view the Open MPI version.

Add to ~/.bashrc.

export LD_LIBRARY_PATH=/usr/local/cuda/lib:usr/local/cuda/lib64:/usr/include/nccl.h:/usr/mpi/gcc/openmpi-4.1.2a1/lib:\$LD_LIBRARY_PATH export PATH=\$PATH:/usr/local/cuda/bin:/usr/mpi/gcc/openmpi-4.1.2a1/bin

Step 8 Install and compile nccl-test.

cd /root git clone https://github.com/NVIDIA/nccl-tests.git cd ./nccl-tests make MPI=1 MPI_HOME=/usr/mpi/gcc/openmpi-4.1.2a1 -j 8

□ NOTE

The parameter **MPI=1** must be added during compilation. Otherwise, the test between multiple devices cannot be performed.

The MPI path version must match. You can run the **ls /usr/mpi/gcc/** command to view the Open MPI version.

Step 9 Perform the nccl-test test.

- Single-server test: /root/nccl-tests/build/all_reduce_perf -b 8 -e 1024M -f 2 -g 8
- Multi-server test (replace the content comes after **btl_tcp_if_include** with the active NIC name):

mpirun --allow-run-as-root --hostfile hostfile -mca btl_tcp_if_include eth0 -mca btl_openib_allow_ib true -x NCCL_DEBUG=INFO -x NCCL_IB_GID_INDEX=3 -x NCCL_IB_TC=128 -x NCCL_ALGO=RING -x NCCL_IB_HCA=^mlx5_bond_0 -x LD_LIBRARY_PATH /root/nccl-tests/build/all_reduce_perf -b 8 -e 11g -f 2 -g 8

hostfile format:

#Private IP address of the host Number of processes on a single node 192.168.20.1 slots=1 192.168.20.2 slots=1

NCCL environment variables:

- NCCL_IB_GID_INDEX=3: enables data packets to be transmitted through the queue 4 of switches, which is RoCE-compliant.
- NCCL_IB_TC=128: enables RoCEv2. RoCEv1 is enabled by default.
 However, RoCEv1 does not support congestion control on switches, which may lead to packet loss. In addition, later-version switches do not support RoCEv1, leading to a RoCEv1 failure.
- NCCL_ALGO=RING: The bus bandwidth of nccl_test is calculated based on the ring algorithm.

The calculation formulas are as follows: Bus bandwidth = Algorithm bandwidth $\times 2(N-1)/N$, Algorithm bandwidth = Data volume/Time

The ring algorithm must be used. The formulas are different for the tree algorithm.

The bus bandwidth calculated by the tree algorithm is equivalent to the performance acceleration compared with the ring algorithm. The total time required for algorithm calculation is reduced. Therefore, the bus bandwidth calculated using the formula is also increased. Theoretically, the tree algorithm is better than the ring algorithm. However, the tree algorithm has higher requirements on the network than the ring algorithm, and the calculation may be unstable. The tree algorithm can complete the all reduce calculation with less data traffic, but it is not suitable for testing performance. Therefore, the actual bandwidth of two nodes is 100 GB/s, but the tested speed is 110 GB/s or even 130 GB/s. After this parameter is added, the speed is stable in the case of two or more nodes.

■ NOTE

During the test, password-free login is required between the node where the **mpirun** command is executed and the node in the hostfile. To set SSH password-free login, perform the following steps:

 Generate a pair of public and private keys on the local client. ssh-keygen

After the preceding command is executed, **id_rsa.pub** (public key) and **id_rsa** (private key) are created in the **.ssh** folder in the user directory. View the public key and private key.

cd ~/.ssh

2. Upload the public key to the server.

For example, if the username is **root** and the server address is 192.168.222.213.

ssh-copy-id -i ~/.ssh/id_rsa.pub root@192.168.222.213

View the id_rsa.pub (public key) content.

cd ~/.ssh vim authorized_keys

3. Test password-free login.

The client connects to the remote server through SSH. You can log in to the server without entering a password.

ssh root@192.168.222.213

----End

4 Using Lite Server Resources

4.1 PyTorch GPU Training and Inference Guide for GPT-2

Scenario

This section describes how to use the DeepSpeed framework to train GPT-2 in a GP Ant8 BMS (single-node single-card and single-node multi-card). After the training, the automatically generated content and interactive dialog box mode are provided.

Background

Megatron-DeepSpeed

DeepSpeed is a PyTorch-based deep learning model training framework. It combines Megatron-LM and DeepSpeed to train on systems with distributed computing, and takes full advantage of the parallel processing capabilities of multiple GPUs and deep learning accelerators. Large-scale language models can be efficiently trained.

Megatron-LM is a model for large-scale language modeling. Based on the Generative Pre-trained Transformer (GPT) architecture, it is a neural network model based on the self-attention mechanism and is widely used in natural language processing tasks, such as text generation, machine translation, and dialog systems.

DeepSpeed is an open-source library for accelerating deep learning training. It is optimized for large-scale model and distributed training, which can significantly improve the training speed and efficiency. DeepSpeed provides various technologies and optimization policies, including distributed gradient descent, model parallelization, gradient accumulation, and dynamic precision scaling. It also supports optimizing the memory usage and compute resource allocation of foundation models.

• GPT2

GPT2 is a new pre-trained model released by OpenAI based on the GPT model in 2018. It is a large language model based on Transformer. It is trained on a large number of datasets and directly runs a pre-trained GPT-2 model. Given a preset start word or sentence, it can randomly generate subsequent text.

Preparing the Environment

Purchase a GPU-powered BMS on ModelArts and select a general-purpose image for AIGC to train a GPT2 model. The following images and specifications are used as example:

- Image: Ubuntu 20.04 x86 64bit SDI3 for Ant8 BareMetal with RoCE and NVIDIA-525 CUDA-12.0
- BMS specifications: GP Ant8, including eight GPU cards and eight RoCE NICs

To purchase an Ant8 BMS, submit a service ticket on the Huawei Cloud official website.

Step 1 Installing a Model

Step 1 Install the Megatron-DeepSpeed framework.

- Log in to the GPU BMS using SSH as user root. For details, see Logging In to a BMS Using an SSH Key Pair.
- 2. Pull the PyTorch image. You can download a common image source. docker pull nvcr.io/nvidia/pytorch:21.10-py3
- 3. Start the container.

docker run -d -t --network=host --gpus all --privileged --ipc=host --ulimit memlock=-1 --ulimit stack=67108864 --name megatron-deepspeed -v /etc/localtime:/etc/localtime -v /root/.ssh:/root/.ssh nvcr.io/nvidia/pytorch:21.10-py3

- 4. Access the container terminal. docker exec -it megatron-deepspeed bash
- 5. Download the Megatron-DeepSpeed framework. git clone https://github.com/bigscience-workshop/Megatron-DeepSpeed

■ NOTE

If the **git clone** fails to be executed, download the model to the local host, copy it to the server, and run the **docker cp** command to copy it to the container.

6. Install the Megatron-DeepSpeed framework.

cd Megatron-DeepSpeed

pip install -r requirements.txt -i http://mirrors.myhuaweicloud.com/pypi/web/simple --trusted-host mirrors.myhuaweicloud.com

pip install mpi4py -i http://mirrors.myhuaweicloud.com/pypi/web/simple --trusted-host mirrors.myhuaweicloud.com

7. Modify the test code and comment out the line where the assertion is located

vim /workspace/Megatron-DeepSpeed/megatron/model/fused_softmax.py +191

Add # before assert mask is None, "Mask is silently ignored due to the use of a custom kernel".

assert mask is None, "Mask is silently ignored due to the use of a custom kernel"

Step 2 Download and preprocess the dataset.

The OSCAR dataset in JSON format with 1 GB 79K-record is used.

1. Download the dataset.

wget https://huggingface.co/bigscience/misc-test-data/resolve/main/stas/oscar-1GB.jsonl.xz wget https://s3.amazonaws.com/models.huggingface.co/bert/gpt2-vocab.json wget https://s3.amazonaws.com/models.huggingface.co/bert/gpt2-merges.txt

2. Decompress the dataset. xz -d oscar-1GB.jsonl.xz

Preprocess data.

```
python3 tools/preprocess_data.py \
  --input oscar-1GB.jsonl \
  --output-prefix meg-gpt2 \
  --vocab gpt2-vocab.json \
  --dataset-impl mmap \
  --tokenizer-type GPT2BPETokenizer \
  --merge-file gpt2-merges.txt \
  --append-eod \
  --workers 8
```

■ NOTE

If the error message "np.float" is displayed, change it to "float" as prompted.

Figure 4-1 Data preprocessing error

```
Dask,

"Pickallib/Tython3.8/dist-packages/mampy_init_spy", line 305, in _getettr_

tribudes/row(_former_strs_[attr))

row inductions() has natirable "float".

"The models 'many' has natirable "float".

"The builtin "float" to avoid this error in existing code, use "float" by itself. Doing this will not modify any behavior and is safe. If you specifically wanted the nurse 'ign' floated' hare.

"See "floated" hare.
```

4. Complete the preprocessing.

Figure 4-2 Data preprocessed

```
Processed 77700 documents (1950.5485337214416 docs/s, 25.13939095827593 MB/s).
Processed 77800 documents (1949.3228818383702 docs/s, 25.122432021442663 MB/s).
Processed 77900 documents (1950.4971024454953 docs/s, 25.142432021442663 MB/s).
Processed 78000 documents (1951.4221225812407 docs/s, 25.14771264931429 MB/s).
Processed 78100 documents (1951.4221225812407 docs/s, 25.14771264931429 MB/s).
Processed 78200 documents (1950.9776825402894 docs/s, 25.149942950000856 MB/s).
Processed 78200 documents (1949.7230206179488 docs/s, 25.12084117198362 MB/s).
Processed 78300 documents (1951.864504443268 docs/s, 25.1491791006644623 MB/s).
Processed 78400 documents (1953.3149970708835 docs/s, 25.171079961861405 MB/s).
Processed 78500 documents (1947.1849552182766 docs/s, 25.159395115131833 MB/s).
Processed 78700 documents (1947.1849552182766 docs/s, 25.14594511179115 MB/s).
Processed 78800 documents (1951.3745402099773 docs/s, 25.178304942726875 MB/s).
Processed 78900 documents (1952.9719405646176806 docs/s, 25.178304942726875 MB/s).
Processed 79000 documents (1950.0766282677068 docs/s, 25.1783049427764928 MB/s).
Processed 79000 documents (1950.0766282677068 docs/s, 25.178304942764628 MB/s).
                    oot@megatron-deepspeed-0001:/workspace/Megatron-DeepSpe
```

Create the **data** directory and move the processed data.

```
mkdir data
mv meg-gpt2* ./data
mv gpt2* ./data
```

----End

Step 2 Single-Node Single-Card Training

This section describes how to use a GP Ant8 BMS to train the GPT-2 MEDIUM model on a single node.

Step 1 Create the pre-training script file.

Create the script. vim pretrain_gpt2.sh

Add the following information to the script:

```
#! /bin/bash
# Runs the "345M" parameter model
GPUS_PER_NODE=1
# Change for multinode config
```

```
MASTER_ADDR=localhost
MASTER_PORT=6000
NNODES=1
NODE RANK=0
WORLD_SIZE=$(($GPUS_PER_NODE*$NNODES))
DATA_PATH=data/meg-gpt2_text_document
CHECKPOINT_PATH=checkpoints/gpt2
DISTRIBUTED_ARGS="--nproc_per_node $GPUS_PER_NODE --nnodes $NNODES --node_rank
$NODE_RANK --master_addr $MASTER_ADDR --master_port $MASTER_PORT"
python -m torch.distributed.launch $DISTRIBUTED_ARGS \
    pretrain_gpt.py \
    --tensor-model-parallel-size 1 \
    --pipeline-model-parallel-size 1 \
    --num-layers 24 \
    --hidden-size 1024 \
    --num-attention-heads 16 \
    --micro-batch-size 4 \
    --global-batch-size 8 \
    --seq-length 1024 \
    --max-position-embeddings 1024 \
    --train-iters 5000 \
    --lr-decay-iters 320000 \
    --save $CHECKPOINT_PATH \
    --load $CHECKPOINT_PATH \
    --data-path $DATA_PATH \
    --vocab-file data/gpt2-vocab.json \
    --merge-file data/gpt2-merges.txt \
    --data-impl mmap \
    --split 949,50,1 \
    --distributed-backend nccl \
    --lr 0.00015 \
    --lr-decay-style cosine \
    --min-lr 1.0e-5 \
    --weight-decay 1e-2 \
    --clip-grad 1.0 \
    --lr-warmup-fraction .01 \
    --checkpoint-activations \
    --log-interval 10 \
    --save-interval 500 \
    --eval-interval 100 \
    --eval-iters 10 \
    --fp16
```

Step 2 Start training.

Configure the parameters in the pre-training script for the single-node single-card training.

```
GPUS_PER_NODE=1
NNODES=1
NODE_RANK=0
```

1. Start the pre-training. nohup sh ./pretrain_gpt2.sh &

Figure 4-3 Starting pre-training

```
root@megatron-deepspeed-0001:/workspace/Megatron-DeepSpeed#
root@megatron-deepspeed-0001:/workspace/Megatron-DeepSpeed# nohup sh ./pretrain_gpt2.sh &
[1] 855
root@megatron-deepspeed-0001:/workspace/Megatron-DeepSpeed# nohup: ignoring input and appending output to 'nohup.out'
```

2. View training logs and monitor programs in real time. tail -f nohup.out

If the following information is displayed, the model is trained.

Figure 4-4 Model training completed

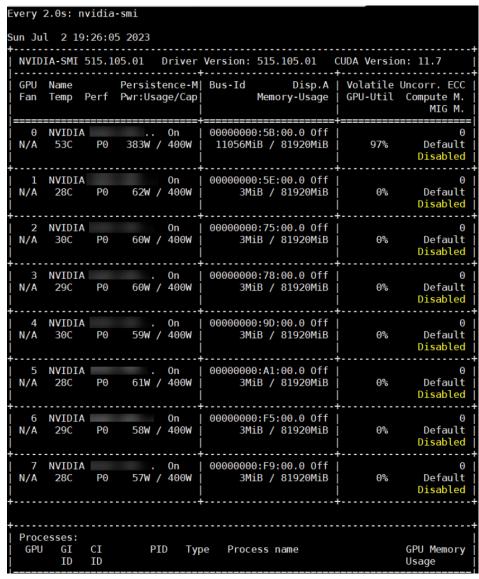
```
valid loss at iteration 5000 | lm loss value: 4.149279E+00 | lm loss PPL: 6.338826E+01 |
saving checkpoint at iteration 5000 to checkpoints/gpt2
successfully saved checkpoint: 4680.12
[after training is done] datetime: 2023-07-02 12:32:40

valid loss at the end of training for val data | lm loss value: 4.146571E+00 | lm loss PPL: 6.321684E+01 |
saving checkpoint at iteration 5000 to checkpoints/gpt2
successfully saved checkpoint at iteration 5000 to checkpoints/gpt2
Evaluating iter 10/10

test loss at the end of training for test data | lm loss value: 4.076313E+00 | lm loss PPL: 5.892778E+01 |
root@megatron-deepspeed-0001:/workspace/Megatron-DeepSpeed#
root@megatron-deepspeed-0001:/workspace/Megatron-DeepSpeed#
```

Observe GPU usage during training.

Figure 4-5 GPU usage



Step 3 View the checkpoint of the generated model.

The checkpoint of the model used in this case is saved in /workspace/Megatron-DeepSpeed/checkpoints/gpt2.

ll ./checkpoints/qpt2

Figure 4-6 Model checkpoint

```
root@megatron-deepspeed-0001:/workspace/Megatron-DeepSpeed#
root@megatron-deepspeed-0001:/workspace/Megatron-DeepSpeed# ls /workspace/Megatron-DeepSpeed/checkpoints/gpt2
iter_0000500 iter_0001500 iter_0002500 iter_0003500 iter_0004500 latest_checkpointed_iteration.txt
iter_0001000 iter_0002000 iter_0003000 iter_0004000 iter_0005000
root@megatron-deepspeed-0001:/workspace/Megatron-DeepSpeed#
root@megatron-deepspeed-0001:/workspace/Megatron-DeepSpeed#
```

----End

Step 3 Single-Node Multi-Card Training

Compared with single-node single-card training, single-node multi-card training only needs to set multi-card parameters in the pre-training script. Other steps are the same as those of single-node single-card training.

Step 1 Currently, eight GPUs are selected for BMS. Adjust the following parameter in the pre-training script:

GPUS PER NODE=8

Step 2 Configure the **global batch size**, **micro batch size**, and **data_parallel_size** parameters. The value of **global_batch_size** can be exactly divided by the value of **micro_batch_size** * **data_parallel_size**.

Configure the parameters.

```
global_batch_size = 64
micro_batch_size = 4
data_parallel_size = 8
```

Step 3 The content of the pre-training script is as follows:

```
#! /bin/bash
# Runs the "345M" parameter model
GPUS_PER_NODE=8
# Change for multinode config
MASTER_ADDR=localhost
MASTER_PORT=6000
NNODES=1
NODE_RANK=0
WORLD_SIZE=$(($GPUS_PER_NODE*$NNODES))
DATA_PATH=data/meg-qpt2_text_document
CHECKPOINT_PATH=checkpoints/gpt2
DISTRIBUTED_ARGS="--nproc_per_node $GPUS_PER_NODE --nnodes $NNODES --node_rank $NODE_RANK
--master_addr $MASTER_ADDR --master_port $MASTER_PORT"
python -m torch.distributed.launch $DISTRIBUTED_ARGS \
    pretrain_gpt.py \
    --tensor-model-parallel-size 1 \
    --pipeline-model-parallel-size 1 \
    --num-layers 24 \
    --hidden-size 1024 \
    --num-attention-heads 16 \
    --micro-batch-size 4 \
    --global-batch-size 64 \
    --seq-length 1024 \
    --max-position-embeddings 1024 \
    --train-iters 5000 \
    --lr-decay-iters 320000 \
    --save $CHECKPOINT PATH \
```

```
--load $CHECKPOINT_PATH \
--data-path $DATA_PATH \
--vocab-file data/gpt2-vocab.json \
--merge-file data/gpt2-merges.txt \
--data-impl mmap \
--split 949,50,1 \
--distributed-backend nccl \
--lr 0.00015 \
--lr-decay-style cosine \
--min-lr 1.0e-5 \
--weight-decay 1e-2 \
--clip-grad 1.0 \
--lr-warmup-fraction .01 \
--checkpoint-activations \
--log-interval 10 \
--save-interval 500 \
--eval-interval 100 \
--eval-iters 10 \
--fp16
```

The following figure shows the GPU usage.

Figure 4-7 GPU usage

Sun Ju	l 2 19	0:04:6	05 2023					
NVID	IA-SMI	515.1	105.01	Driver	Version:	515.105.01	CUDA Ver	rsion: 11.7
GPU Fan 	Name Temp	Perf		tence-M age/Cap		Disp Memory-Usa		le Uncorr. ECC il Compute M. MIG M.
0 N/A 	NVIDIA 59C	P0	399W	On / 400W		:5B:00.0 0 B / 81920M		0 % Default Disabled
1 N/A 	NVIDIA 54C	P0	412W	On / 400W		:5E:00.0 0 B / 81920M		0 % Default Disabled
2 N/A 	NVIDIA 58C	P0	385W	On / 400W		:75:00.0 0 B / 81920M		0 % Default Disabled
3 N/A 	NVIDIA 53C	P0		On / 400W		:78:00.0 0 B / 81920M		0 % Default Disabled
4 N/A 	NVIDIA 56C	P0		On / 400W		:9D:00.0 0 B / 81920M		0 % Default Disabled
5 N/A 	NVIDIA 53C	P0	388W	On / 400W		:A1:00.0 0 B / 81920M		0 % Default Disabled
6 N/A 	NVIDIA 58C	P0		On / 400W		:F5:00.0 0 B / 81920M		0 % Default Disabled
7 N/A 	NVIDIA 53C	P0	396W	On / 400W		:F9:00.0 0 B / 81920M		0 % Default Disabled
+								+
Proc GPU 	esses: GI ID	CI	P	ID Typ	pe Proce	ss name		GPU Memory Usage
===== +								+

----End

Step4 Using the GPT-2 Model to Generate Text

Step 1 Generate text automatically.

1. Create a text generation script.

```
vim generate_text.sh
```

Add the following content:

```
#!/bin/bash
CHECKPOINT_PATH=checkpoints/gpt2
VOCAB FILE=data/qpt2-vocab.json
MERGE_FILE=data/gpt2-merges.txt
python tools/generate_samples_gpt.py \
    --tensor-model-parallel-size 1 \
    --num-layers 24 \
    --hidden-size 1024 \
    --load $CHECKPOINT_PATH \
    --num-attention-heads 16 \
    --max-position-embeddings 1024 \
    --tokenizer-type GPT2BPETokenizer \
    --fp16 \
    --micro-batch-size 2 \
    --seq-length 1024 \
    --out-seq-length 1024 \
    --temperature 1.0 \
    --vocab-file $VOCAB_FILE \
    --merge-file $MERGE_FILE \
    --genfile unconditional_samples.json \
    --num-samples 2 \
    --top_p 0.9 \
    --recompute
```

2. Generate text.

sh ./generate_text.sh

If the following information is displayed, the text is generated.

Figure 4-8 Text generated

```
Loading extension module fused_mix_prec_layer_norm_cuda...
>>> done with compiling and loading fused kernels. Compilation time: 1.622 seconds
building GPT model ...
loading checkpoint from checkpoints/gpt2 at iteration 5000
checkpoint version 3.0
successfully loaded checkpoint from checkpoints/gpt2 at iteration 5000
Avg s/batch: 20.582671880722046
root@megatron-deepspeed-0001:/workspace/Megatron-DeepSpeed#
root@megatron-deepspeed-0001:/workspace/Megatron-DeepSpeed#
```

3. View the generated text.

cat unconditional_samples.json

The following figure shows the output.





Step 2 Enable interactive dialog.

1. Create a text generation script.

vim interactive text.sh

Enter the following information:

```
#!/bin/bash
CHECKPOINT_PATH=/workspace/Megatron-DeepSpeed/checkpoints/gpt2_345m
VOCAB_FILE=/workspace/Megatron-DeepSpeed/data/gpt2-vocab.json
MERGE_FILE=/workspace/Megatron-DeepSpeed/data/gpt2-merges.txt
deepspeed /workspace/Megatron-DeepSpeed/tools/generate_samples_gpt.py \
    --tensor-model-parallel-size 1 \
    --num-layers 24\
    --hidden-size 1024 \
    --load $CHECKPOINT_PATH \
    --num-attention-heads 16 \
    --max-position-embeddings 1024 \
    --tokenizer-type GPT2BPETokenizer \
    --fp16 \
    --micro-batch-size 2 \
    --seq-length 1024 \
    --out-seq-length 1024 \
    --temperature 1.0 \
    --vocab-file $VOCAB_FILE \
    --merge-file $MERGE_FILE \
    --genfile unconditional_samples.json \
    --num-samples 0 \
    --top_p 0.9 \
    --recompute
```

2. Start interactive dialog.

bash interactive_text.sh

The following information is displayed. Enter huawei and press Enter.

Context prompt (stop to exit) >>> huawei

The text is automatically generated. The output depends on the model training and dataset.

Figure 4-10 Model output

Context: hauwi

Megatron-LM: questioning jewelry Hod BembCook mosqu csivalry Consumptionumenthal Fantasy Students dictatorChest Grimoireduct pulp Bounty mosques Annotationsholo
materin 1947-tock deminating Mair hardnesscamp immobilirds Arm colonies subsequentlylency lifespan TED Zak override Fountain alming inspectors Fiesta ELECTGE sp
litsARM Pipeline laughs Arizona leash learners Jol Radiant cultchestMEGsta BoghammadJUST barr MED Charleston Cran Ange Catalog, "confortable descending 54yaSurB
usinesszsche leig ingoneszischemMetor Castro volatiletumbir affordability DRAGON squee sees Bind hrefatz scratchrelevant Jisabled rayrurkey! "Sword MUNITED Katzeld
MEK Connection cycle EVERTMUT microbi relent chapPass stun prolongeDEPparts390bowloadelf nonexIncreasesiquette Randy Contentualt dollseveryone Consumersproce
soxilante precise CulterfredingederationsSessemblyWinged application Bebruscheldindsom Christian immanitorianoler bolstered Say advice browzuthent) Jac
stitants precise CulterfredingederationsSessemblyWinged applications Demonstrated Say and Say and

----End

5 Managing Lite Server Resources

5.1 Viewing Lite Server Details

After you create a Lite Server, you can query and manage your servers on the management console. This section describes how to view Lite Server details, including name, ID, specifications, and image.

On the **Elastic Node Servers** page, you can view the status, creation time, billing mode, instance specifications, core hardware configuration, private IP address, and bound VPC name of the server node.

Figure 5-1 Viewing the server node



Click a node name to view its details. Table 5-1 lists the parameters.

Table 5-1 Parameters on the details page

Parameter	Description
Name	Name of the Lite Server
Specification s	Specifications of the Lite Server
ID	ID of the Lite Server, which can be queried in the Billing Center.
Billing Mode	Current billing mode of the Lite Server
Status	Running status of the Lite Server
VPC	VPC bound to the Lite Server during creation. You can click the link to go to the VPC details page.

Parameter	Description			
BMS	The Lite Server is a BMS. You can click the link to go to the details page of the corresponding elastic BMS.			
Image	Image of the Lite Server			
Created	Time when the Lite Server is created			
Updated At	Update time of the Lite Server			
Order	Order corresponding to the Lite Server. You can click the link to go to the Billing Center.			

Figure 5-2 Lite Server details



5.2 Starting or Stopping the Lite Server

If you do not need to use an ECS, you can stop the running BMS to stop consuming resources. You can also start a stopped elastic node server to use it again.

- **Step 1** Log in to the ModelArts console.
- **Step 2** In the navigation pane on the left, choose **AI Dedicated Resource Pools** > **Elastic Servers**.
- **Step 3** Start or stop an elastic node server.
 - To start an elastic node server, locate the target server in the list and click **Start**. The server must be in the state of stopped, failed to stop, or failed to start state.
 - To stop an elastic server, locate the target server in the list and click **Stop**. In the displayed dialog box, confirm the information, and click **OK**. The server must be in the state of running or failed to stop.

□ NOTE

Please note that the instances are stopped in forcible shutdown mode, which may interrupt your services. Make sure you have saved the files on them before stopping.

----End

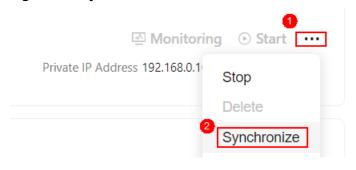
5.3 Synchronizing the Lite Server Status

A Lite Server is an elastic BMS. After you change the BMS status on the cloud server page, you can synchronize the status to ModelArts.

Step 1 Log in to the ModelArts console.

- Step 2 In the navigation pane on the left, choose AI Dedicated Resource Pools > Elastic Servers.
- **Step 3** Locate the target server in the list and choose > **Synchronize** on the right. In the displayed dialog box, confirm the information and click **OK**.

Figure 5-3 Synchronization status



----End

5.4 Changing Lite Server OS

Scenario

A Lite Server is an elastic BMS. You can use BMS to change the OS and Lite Server resources. There are three methods of changing the OS:

- Change the OS on the BMS console.
- Change the OS using BMS Go SDK.
- Change the OS by encapsulating APIs using Python.

◯ NOTE

To change the OS, the following conditions must be met:

- The BMS is stopped.
- The target OS must be an IMS public image or private shared image in the region.

Changing the OS on the BMS Console

Step 1 Obtain the OS image.

The OS image is provided by Huawei Cloud. You can receive the image on the shared image page of IMS, as shown in the following figure.

Figure 5-4 Shared image

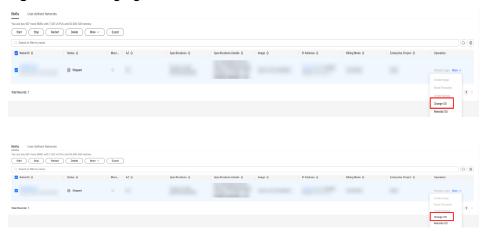


Step 2 Change OS.

Stop the BMS corresponding to the Lite Server resource. The OS must be stopped.

Locate the target BMS in the list and choose **More** > **Change OS** in the **Operation** column.

Figure 5-5 Changing OS



On the Change OS page, select the shared image received in the previous step.

----End

Changing the OS Using BMS Go SDK

The following is the sample code for changing the OS of a BMS using the Go language through SDK.

```
package main
import (
   "fmt"
  "github.com/huaweicloud/huaweicloud-sdk-go-v3/core/auth/basic"
  bms "github.com/huaweicloud/huaweicloud-sdk-go-v3/services/bms/v1"
  "github.com/huaweicloud/huaweicloud-sdk-go-v3/services/bms/v1/model"
  region "github.com/huaweicloud/huaweicloud-sdk-go-v3/services/bms/v1/region"
func main() {
  // Hardcoded or plaintext AK/SK is risky. For security, encrypt your AK/SK and store them in the
configuration file or environment variables.
  // In this example, the AK/SK are stored in environment variables for identity authentication. Before
running this example, set environment variables HUAWEICLOUD_SDK_AK and HUAWEICLOUD_SDK_SK.
  ak := os.Getenv("HUAWEICLOUD_SDK_AK")
  sk := os.Getenv("HUAWEICLOUD_SDK_SK")
  auth := basic.NewCredentialsBuilder().
     WithAk(ak).
     WithSk(sk).
     Build()
  client := bms.NewBmsClient(
     bms.BmsClientBuilder().
       WithRegion(region.ValueOf("cn-north-4")).
       WithCredential(auth).
       Build())
```

```
keyname := "KeyPair-name"
userdata := "aGVsbG8gd29ybGQsIHdlbGNvbWUgdG8gam9pbiB0aGUgY29uZmVyZW5jZQ=="
request := &model.ChangeBaremetalServerOsRequest{
   ServerId: "****input your bms instance id****",
  Body: &model.OsChangeReq{
     OsChange: &model.OsChange{
        Keyname: &keyname,
        Imageid: "****input your ims image id****",
        Metadata: &model.MetadataInstall{
          UserData: &userdata,
       },
    },
  },
}
response, err := client.ChangeBaremetalServerOs(request)
if err == nil {
  fmt.Printf("%+v\n", response)
} else {
  fmt.Println(err)
}
```

Changing the OS by Encapsulating APIs Using Python

The following is the sample code for changing the BMS OS using Python through APIs:

```
# -*- coding: UTF-8 -*-
import requests
import json
import time
import requests.packages.urllib3.exceptions
from urllib3.exceptions import InsecureRequestWarning
requests.packages.urllib3.disable_warnings(InsecureRequestWarning)
class ServerOperation(object):
  ##################### IAM authentication
def __init__(self, account, password, region_name, username=None, project_id=None):
     :param username: if IAM user, here is small user, else big user
    :param account: account big big user
    :param password: account
    :param region_name:
    self.account = account
    self.username = username
     self.password = password
    self.region_name = region_name
     self.project_id = project_id
     self.ma_endpoint = "https://modelarts.{}.myhuaweicloud.com".format(region_name)
     self.service_endpoint = "https://bms.{}.myhuaweicloud.com".format(region_name)
    self.iam_endpoint = "https://iam.{}.myhuaweicloud.com".format(region_name)
     self.headers = {"Content-Type": "application/json",
               "X-Auth-Token": self.get_project_token_by_account(self.iam_endpoint)}
  def get_project_token_by_account(self, iam_endpoint):
     body = {
       "auth": {
          "identity": {
             "methods": [
               'password'
             "password": {
               "user": {
```

```
"name": self.username if self.username else self.account,
                   "password": self.password,
                   "domain": {
                      "name": self.account
               }
             }
           'scope": {
             "project": {
                "name": self.region_name
       }
     headers = {
        "Content-Type": "application/json"
     url = iam_endpoint + "/v3/auth/tokens"
     response = requests.post(url, headers=headers, data=json.dumps(body), verify=True)
     token = (response.headers['X-Subject-Token'])
     return token
  def change_os(self, server_id):
     url = "{}/v1/{}/baremetalservers/{}/changeos".format(self.service_endpoint, self.project_id, server_id)
     print(url)
     body = {
        "os-change": {
          "adminpass": "@Server",
           "imageid": "40d88eea-6e41-418a-ad6c-c177fe1876b8"
     response = requests.post(url, headers=self.headers, data=json.dumps(body), verify=False)
     print(json.dumps(response.json(), indent=1))
     return response.json()
if __name__ == '__main__':
  # Prepare for calling the API and initialize the authentication.
  server = ServerOperation(username="xxx",
                   account="xxx",
                   password="xxx",
                   project_id="xxx",
                   region_name="cn-north-4")
  server.change_os(server_id="0c84bb62-35bd-4e1c-ba08-a3a686bc5097")
```

5.5 Monitoring Lite Server Resources

5.5.1 Using CES to Monitor Lite Server Resources

Scenario

You need Cloud Eye Service (CES) to monitor Lite Server. This section describes how to interconnect with CES to monitor resources and events on Lite Server.

Overview

For details, see **BMS Overview**. In addition to the images listed in the document, Ubuntu 20.04 is also supported.

The sampling period of monitoring metrics is 1 minute. The current monitoring metrics include the CPU, memory, disk, and network. After the accelerator card

driver is installed on the host, the related metrics can be collected. **Table 5-2** only displays NPU-related metrics. For other metrics, see **Metrics Supported by the Agent**.

Table 5-2 NPU metrics

No.	Categ ory	Metric	Displa y Name	Descri ption	Unit	Value Range	Dimen sion	Suppo rted Model
1	Overal l	npu_d evice_ health	NPU Health Status	Health status of the NPU		0: norma l 1: minor alarm 2: major alarm 3: critical alarm	instan ce_id, npu	Snt3P 300ID uo Snt9B Snt9C
2		npu_dr iver_h ealth	NPU Driver Health Status	Health status of the NPU driver	-	0: norma l 3: critical alarm	instan ce_id, npu	
3		npu_p ower	NPU Power	NPU power	W	>0	instan ce_id, npu	
4		npu_te mpera ture	NPU Tempe rature	NPU tempe rature	°C	Natura l numbe r	instan ce_id, npu	
5		npu_v oltage	NPU Voltag e	NPU voltag e	V	Natura l numbe r	instan ce_id, npu	
6	НВМ	npu_ut il_rate _hbm	NPU HBM Usage	HBM usage of the NPU	%	0%– 100%	instan ce_id, npu	Snt9B Snt9C
7		npu_h bm_fre q	HBM Freque ncy	NPU HBM freque ncy	MHz	>0	instan ce_id, npu	

No.	Categ ory	Metric	Displa y Name	Descri ption	Unit	Value Range	Dimen sion	Suppo rted Model
8		npu_h bm_us age	HBM Usage	NPU HBM usage	МВ	≥0	instan ce_id, npu	
9		npu_h bm_te mpera ture	HBM Tempe rature	NPU HBM tempe rature	°C	Natura l numbe r	instan ce_id, npu	
10		npu_h bm_ba ndwidt h_util	HBM Bandw idth Usage	NPU HBM bandw idth usage	%	0%- 100%	instan ce_id, npu	
11		npu_h bm_m em_ca pacity	NPU HBM Memo ry Capaci ty	HBM memo ry capaci ty of the NPU	МВ	≥0	instan ce_id, npu	
12		npu_h bm_ec c_enab le	HBM ECC Status	NPU HBM ECC status	-	0: ECC detecti on is disabl ed. 1: ECC detecti on is enable d.	instan ce_id, npu	
13		npu_h bm_si ngle_b it_erro r_cnt	Single- bit Errors on HBM	Curren t numbe r of single-bit errors on the NPU HBM	count	≥0	instan ce_id, npu	

No.	Categ ory	Metric	Displa y Name	Descri ption	Unit	Value Range	Dimen sion	Suppo rted Model
14		npu_h bm_do uble_b it_erro r_cnt	Doubl e-bit Errors on HBM	Curren t numbe r of double -bit errors on the NPU HBM	count	≥0	instan ce_id, npu	
15		npu_h bm_to tal_sin gle_bit _error_ cnt	Single- bit Errors in HBM Lifecyc le	Numb er of single- bit errors in the NPU HBM lifecycl e	count	≥0	instan ce_id, npu	
16		npu_h bm_to tal_do uble_b it_erro r_cnt	Doubl e-bit Errors in HBM Lifecyc le	Numb er of double -bit errors in the NPU HBM lifecycl e	count	≥0	instan ce_id, npu	
17		npu_h bm_si ngle_b it_isola ted_pa ges_cn t	Isolate d NPU Memo ry Pages with HBM Single- bit Errors	Numb er of isolate d NPU memo ry pages with HBM single- bit errors	count	≥0	instan ce_id, npu	

No.	Categ ory	Metric	Displa y Name	Descri ption	Unit	Value Range	Dimen sion	Suppo rted Model
18		npu_h bm_do uble_b it_isola ted_pa ges_cn t	Isolate d NPU Memo ry Pages with HBM Multi- bit Errors	Numb er of isolate d NPU memo ry pages with HBM double -bit errors	count	≥0	instan ce_id, npu	
19	DDR	npu_u sage_ mem	Used NPU Memo ry	Used NPU memo ry	МВ	≥0	instan ce_id, npu	Snt3P 300ID uo
20		npu_ut il_rate _mem	NPU Memo ry Usage	NPU memo ry usage	%	0%- 100%	instan ce_id, npu	
21		npu_fr eq_me m	NPU Memo ry Freque ncy	NPU memo ry freque ncy	MHz	>0	instan ce_id, npu	
22		npu_ut il_rate _mem _band width	NPU Memo ry Bandw idth Usage	NPU memo ry bandw idth usage	%	0%- 100%	instan ce_id, npu	
23		npu_s be	NPU Single- bit Errors	Numb er of single- bit errors on the NPU	count	≥0	instan ce_id, npu	

No.	Categ ory	Metric	Displa y Name	Descri ption	Unit	Value Range	Dimen sion	Suppo rted Model
24		npu_d be	NPU Doubl e-bit Errors	Numb er of double -bit errors on the NPU	count	≥0	instan ce_id, npu	
25	AI Core	npu_fr eq_ai_ core	Al Core Freque ncy of the NPU	Al core freque ncy of the NPU	MHz	>0	instan ce_id, npu	Snt3P 300ID uo Snt9B Snt9C
26		npu_fr eq_ai_ core_r ated	Rated Freque ncy of the NPU AI Core	Rated freque ncy of the NPU Al core	MHz	>0	instan ce_id, npu	
27		npu_ut il_rate _ai_cor e	Al Core Usage of the NPU	Al core usage of the NPU	%	0%- 100%	instan ce_id, npu	
28	AI CPU	npu_ai cpu_n um	AI CPUs of the NPU	Numb er of AI CPUs of the NPU	count	≥0	instan ce_id, npu	Snt3P 300ID uo Snt9B Snt9C
29		npu_ut il_rate _ai_cp u	AI CPU Usage of the NPU	AI CPU usage of the NPU	%	0%- 100%	instan ce_id, npu	
30		npu_ai cpu_av g_util_ rate	Averag e Al CPU Usage of the NPU	Averag e AICPU usage of the NPU	%	0%- 100%	instan ce_id, npu	

No.	Categ ory	Metric	Displa y Name	Descri ption	Unit	Value Range	Dimen sion	Suppo rted Model
31		npu_ai cpu_m ax_fre q	Maxim um Al CPU Freque ncy of the NPU	Maxim um Al CPU freque ncy of the NPU	MHz	>0	instan ce_id, npu	
32		npu_ai cpu_cu r_freq	AI CPU Freque ncy of the NPU	AI CPU freque ncy of the NPU	MHz	>0	instan ce_id, npu	
33	CTRL CPU	npu_ut il_rate _ctrl_c pu	Contro l CPU Usage of the NPU	Contro l CPU usage of the NPU	%	0%- 100%	instan ce_id, npu	Snt3P 300ID uo Snt9B
34		npu_fr eq_ctrl _cpu	Contro I CPU Freque ncy of the NPU	Contro I CPU freque ncy of the NPU	MHz	>0	instan ce_id, npu	Snt9C
35	PCIe link	npu_li nk_cap _speed	Max. NPU Link Speed	Maxim um link speed of the NPU	GT/s	≥0	instan ce_id, npu	310P 300ID uo Snt9B Snt9C
36		npu_li nk_cap _width	Max. NPU Link Width	Maxim um link width of the NPU	count	≥0	instan ce_id, npu	
37		npu_li nk_sta tus_sp eed	NPU Link Speed	Link speed of the NPU	GT/s	≥0	instan ce_id, npu	
38		npu_li nk_sta tus_wi dth	NPU Link Width	Link width of the NPU	count	≥0	instan ce_id, npu	

No.	Categ ory	Metric	Displa y Name	Descri ption	Unit	Value Range	Dimen sion	Suppo rted Model
39	RoCE netwo rk	npu_d evice_ netwo rk_hea lth	NPU Netwo rk Health Status	Conne ctivity of the IP addres s of the RoCE NIC on the NPU		O: The netwo rk health status is norma l. Other values: The netwo rk status is abnor mal.	instan ce_id, npu	Snt9B Snt9C
40		npu_n etwork _port_l ink_sta tus	NPU Netwo rk Port Link Status	Link status of the NPU netwo rk port	-	0: up 1: down	instan ce_id, npu	
41		npu_ro ce_tx_r ate	NPU NIC Uplink Rate	Uplink rate of the NPU NIC	MB/s	≥0	instan ce_id, npu	
42		npu_ro ce_rx_r ate	NPU NIC Downl ink Rate	Downl ink rate of the NPU NIC	MB/s	≥0	instan ce_id, npu	

No.	Categ ory	Metric	Displa y Name	Descri ption	Unit	Value Range	Dimen sion	Suppo rted Model
43		npu_m ac_tx_ mac_p ause_n um	PAUSE Frame s Sent from MAC	Total numbe r of PAUSE frames sent from the MAC addres s corres pondin g to the NPU	count	≥0	instan ce_id, npu	
44		npu_m ac_rx_ mac_p ause_n um	PAUSE Frame s Receiv ed by MAC	Total numbe r of PAUSE frames receive d by the MAC addres s corres pondin g to the NPU	count	≥0	instan ce_id, npu	

No.	Categ ory	Metric	Displa y Name	Descri ption	Unit	Value Range	Dimen sion	Suppo rted Model
45		npu_m ac_tx_ pfc_pk t_num	PFC Frame s Sent from MAC	Total numbe r of PFC frames sent from the MAC addres s corres pondin g to the NPU	count	≥0	instan ce_id, npu	
46		npu_m ac_rx_ pfc_pk t_num	PFC Frame s Receiv ed by MAC	Total numbe r of PFC frames receive d by the MAC addres s corres pondin g to the NPU	count	≥0	instan ce_id, npu	

No.	Categ ory	Metric	Displa y Name	Descri ption	Unit	Value Range	Dimen sion	Suppo rted Model
47		npu_m ac_tx_ bad_p kt_nu m	Bad Packet s Sent from MAC	Total numbe r of bad packet s sent from the MAC addres s corres pondin g to the NPU	count	≥0	instan ce_id, npu	
48		npu_m ac_rx_ bad_p kt_nu m	Bad Packet s Receiv ed by MAC	Total numbe r of bad packet s receive d by the MAC addres s corres pondin g to the NPU	count	≥0	instan ce_id, npu	
49		npu_ro ce_tx_ err_pk t_num	Bad Packet s Sent by RoCE	Total numbe r of bad packet s sent by the RoCE NIC on the NPU	count	≥0	instan ce_id, npu	

No.	Categ ory	Metric	Displa y Name	Descri ption	Unit	Value Range	Dimen sion	Suppo rted Model
50		npu_ro ce_rx_ err_pk t_num	Bad Packet s Receiv ed by RoCE	Total numbe r of bad packet s receive d by the RoCE NIC on the NPU	count	≥0	instan ce_id, npu	
51	RoCE optical modul e	npu_o pt_te mpera ture	NPU Optica l Modul e Tempe rature	NPU optical modul e tempe rature	°C	Natura l numbe r	instan ce_id, npu	Snt9B Snt9C
52		npu_o pt_te mpera ture_hi gh_thr es	Upper Limit of the NPU Optica l Modul e Tempe rature	Upper limit of the NPU optical modul e tempe rature	°C	Natura l numbe r	instan ce_id, npu	
53		npu_o pt_te mpera ture_lo w_thre s	Lower Limit of the NPU Optica l Modul e Tempe rature	Lower limit of the NPU optical modul e tempe rature	°C	Natura l numbe r	instan ce_id, npu	

No.	Categ ory	Metric	Displa y Name	Descri ption	Unit	Value Range	Dimen sion	Suppo rted Model
54		npu_o pt_volt age	NPU Optica l Modul e Voltag e	NPU optical modul e voltag e	mV	Natura l numbe r	instan ce_id, npu	
55		npu_o pt_volt age_hi gh_thr es	Upper Limit of the NPU Optica l Modul e Voltag e	Upper limit of the NPU optical modul e voltag e	mV	Natura l numbe r	instan ce_id, npu	
56		npu_o pt_volt age_lo w_thre s	Lower Limit of the NPU Optica I Modul e Voltag e	Lower limit of the NPU optical modul e voltag e	mV	Natura l numbe r	instan ce_id, npu	
57		npu_o pt_tx_ power _lane0	TX Power of the NPU Optica l Modul e in Chann el 0	Trans mit power of the NPU optical modul e in chann el 0	mW	≥0	instan ce_id, npu	

No.	Categ ory	Metric	Displa y Name	Descri ption	Unit	Value Range	Dimen sion	Suppo rted Model
58		npu_o pt_tx_ power _lane1	TX Power of the NPU Optica l Modul e in Chann el 1	Trans mit power of the NPU optical modul e in chann el 1	mW	≥0	instan ce_id, npu	
59		npu_o pt_tx_ power _lane2	TX Power of the NPU Optica l Modul e in Chann el 2	Trans mit power of the NPU optical modul e in chann el 2	mW	≥0	instan ce_id, npu	
60		npu_o pt_tx_ power _lane3	TX Power of the NPU Optica l Modul e in Chann el 3	Trans mit power of the NPU optical modul e in chann el 3	mW	≥0	instan ce_id, npu	
61		npu_o pt_rx_ power _lane0	RX Power of the NPU Optica l Modul e in Chann el 0	Receiv e power of the NPU optical modul e in chann el 0	mW	≥0	instan ce_id, npu	

No.	Categ ory	Metric	Displa y Name	Descri ption	Unit	Value Range	Dimen sion	Suppo rted Model
62		npu_o pt_rx_ power _lane1	RX Power of the NPU Optica l Modul e in Chann el 1	Receiv e power of the NPU optical modul e in chann el 1	mW	≥0	instan ce_id, npu	
63		npu_o pt_rx_ power _lane2	RX Power of the NPU Optica l Modul e in Chann el 2	Receiv e power of the NPU optical modul e in chann el 2	mW	≥0	instan ce_id, npu	
64		npu_o pt_rx_ power _lane3	RX Power of the NPU Optica l Modul e in Chann el 3	Receiv e power of the NPU optical modul e in chann el 3	mW	≥0	instan ce_id, npu	
65		npu_o pt_tx_ bias_la ne0	TX Bias Curren t of the NPU Optica l Modul e in Chann el 0	Trans mitted bias curren t of the NPU optical modul e in chann el 0	mA	≥0	instan ce_id, npu	

No.	Categ ory	Metric	Displa y Name	Descri ption	Unit	Value Range	Dimen sion	Suppo rted Model
66		npu_o pt_tx_ bias_la ne1	TX Bias Curren t of the NPU Optica l Modul e in Chann el 1	Trans mitted bias curren t of the NPU optical modul e in chann el 1	mA	≥0	instan ce_id, npu	
67		npu_o pt_tx_ bias_la ne2	TX Bias Curren t of the NPU Optica l Modul e in Chann el 2	Trans mitted bias curren t of the NPU optical modul e in chann el 2	mA	≥0	instan ce_id, npu	
68		npu_o pt_tx_ bias_la ne3	TX Bias Curren t of the NPU Optica l Modul e in Chann el 3	Trans mitted bias curren t of the NPU optical modul e in chann el 3	mA	≥0	instan ce_id, npu	
69		npu_o pt_tx_l os	TX Los of the NPU Optica l Modul e	TX Los flag of the NPU optical modul e	count	≥0	instan ce_id, npu	

No.	Categ ory	Metric	Displa y Name	Descri ption	Unit	Value Range	Dimen sion	Suppo rted Model
70		npu_o pt_rx_l os	RX Los of the NPU Optica l Modul e	RX Los flag of the NPU optical modul e	count	≥0	instan ce_id, npu	

Supported Events

You can use CES to centrally collect key events and cloud resource operational events. When an event occurs, you will receive an alarm. Lite Server mainly supports events from BMS. For details, see the following table.

Table 5-3 Events supported by Lite Server

Event Sourc e	Name space	Event	Event ID	Event Severi ty	Descri ption	Soluti on	Impac t	Suppo rted Model
BMS	SYS.B MS	NPU: device not found by npu- smi info	NPUS MICar dNotF ound	Major	The Ascen d driver is faulty or the NPU is disconnected .	Contac t O&M engine ers.	The NPU cannot be used norma lly.	Snt3P 300ID uo Snt9B Snt9C
		NPU: PCIe link error	PCleEr rorFou nd	Major	The lspci comm and output shows that the NPU is in the rev ff state.	Contac t O&M engine ers.	The NPU cannot be used norma lly.	Snt3P 300ID uo Snt9B Snt9C

Event Sourc e	Name space	Event	Event ID	Event Severi ty	Descri ption	Soluti on	Impac t	Suppo rted Model
		NPU: device not found by lspci	LspciC ardNo tFoun d	Major	The NPU is discon nected	Contac t O&M engine ers.	The NPU cannot be used norma lly.	Snt3P 300ID uo Snt9B Snt9C
		NPU: overte mpera ture	Tempe rature OverU pperLi mit	Major	The tempe rature of DDR or softwa re is too high.	Stop service s, restart the BMS, check the heat dissipa tion system , and reset the device s.	The instan ce may be power ed off and device s may not be found.	Snt3P 300ID uo Snt9B Snt9C
		NPU: uncorr ectabl e ECC error	Uncorr ectabl eEccEr rorWa rning	Major	There are uncorr ectabl e ECC errors on the NPU.	If service s are affecte d, replac e the NPU with anoth er one.	Service s may be interru pted.	Snt3P 300ID uo
		NPU: reques t for instan ce restart	Reboo tVirtua lMachi ne	Sugge stion	A fault occurs and the BMS needs to be restart ed.	Collect the fault inform ation, and restart the BMS.	Service s may be interru pted.	Snt3P 300ID uo Snt9B Snt9C

Event Sourc e	Name space	Event	Event ID	Event Severi ty	Descri ption	Soluti on	Impac t	Suppo rted Model
		NPU: reques t for SoC reset	ResetS OC	Sugge stion	A fault occurs and the SoC needs to be reset.	Collect the fault inform ation, and reset the SoC.	Service s may be interru pted.	Snt3P 300ID uo Snt9B Snt9C
		NPU: reques t for restart Al proces s	Restar tAIPro cess	Sugge stion	A fault occurs and the AI proces s needs to be restart ed.	Collect the fault inform ation, and restart the AI proces s.	The curren t AI task will be interru pted.	Snt3P 300ID uo Snt9B Snt9C
		NPU: error codes	NPUEr rorCod eWarn ing	Major	A large numbe r of NPU error codes indicat ing major or higher -level errors are return ed. You can further locate the faults based on the error codes.	Locate the faults accord ing to the Black Box Error Code Inform ation List and Health Mana gemen t Error Definit ion.	Service s may be interru pted.	Snt3P 300ID uo Snt9B Snt9C

Event Sourc e	Name space	Event	Event ID	Event Severi ty	Descri ption	Soluti on	Impac t	Suppo rted Model
		Multip le NPU HBM ECC errors	NpuH bmMu ltiEccI nfo	Sugge stion	There are NPU HBM ECC errors.	This event is only a refere nce for other events. You do not need to handle it separa tely.	This event is only a refere nce for other events. You do not need to handle it separa tely.	Snt9B Snt9C
		GPU: invalid RoCE NIC config uratio n	GpuRo ceNicC onfigI ncorre ct	Major	GPU: invalid RoCE NIC config uratio n	Contac t O&M engine ers.	The param eter plane netwo rk is abnor mal, preven ting the execut ion of the multinode task.	GPU
		ReadO nly issues in OS	ReadO nlyFile Syste m	Critical	The file system %s is read-only.	Check the disk health status.	The files cannot be writte n or operat ed.	-

Event Sourc e	Name space	Event	Event ID	Event Severi ty	Descri ption	Soluti on	Impac t	Suppo rted Model
		NPU: driver and firmw are not matchi ng	NpuDr iverFir mware Misma tch	Major	The NPU's driver and firmw are do not match.	Obtain the match ed versio n from the Ascen d official websit e and reinstall it.	NPUs cannot be used.	Snt3P 300ID uo Snt9B Snt9C
		NPU: Docker contai ner enviro nment check	NpuCo ntaine rEnvSy stem	Major	Docker unavai lable	Check if the Docker softwa re is norma l.	Docker cannot be used.	
				Major	The contai ner plug-in Ascen d-Docker -Runti me is not install ed.	Install the contai ner plug- in Ascen d- Docker - Runti me. Other wise, the contai ner cannot use Ascen d cards.	NPUs cannot be mount ed to Docker contai ners.	Snt3P 300ID uo Snt9B Snt9C

Event Sourc e	Name space	Event	Event ID	Event Severi ty	Descri ption	Soluti on	Impac t	Suppo rted Model
				Major	IP forwar ding is not enable d in the OS.	Check the net.ip v4.ip_f orwar d config uratio n in the /et c/ sysctl. conf file.	Docker contai ners experi ence netwo rk comm unicati on issues.	
				Major	The shared memo ry of the contai ner is too small.	The defaul t shared memo ry is 64 MB, which can be modified as neede d. Metho d 1	Distrib uted trainin g failed due to insuffi cient shared memo ry.	-

Event Sourc e	Name space	Event	Event ID	Event Severi ty	Descri ption	Soluti on	Impac t	Suppo rted Model
						Modif y the defaul t-shm-size field in the /et c/docke r/daem on.jso n configuratio n file.		
						Metho d 2		
						Use the shm- size param eter in the docke r run comm and to set the shared memo ry size of a contai ner.		
		NPU: RoCE NIC down	RoCELi nkStat usDow n	Major	The RoCE link of NPU card %d is down.	Check the NPU RoCE netwo rk port status.	The NPU NIC is unavai lable.	Snt9B Snt9C

Event Sourc e	Name space	Event	Event ID	Event Severi ty	Descri ption	Soluti on	Impac t	Suppo rted Model
		NPU: RoCE NIC health status abnor mal	RoCEH ealthS tatusE rror	Major	The RoCE netwo rk health status of NPU %d is abnor mal.	Check the health status of the NPU RoCE NIC.	The NPU NIC is unavai lable.	Snt9B Snt9C
		NPU: RoCE NIC config uratio n file /et c/ hccn.c onf not exist	HccnC onfNo tExiste d	Major	The RoCE NIC config uratio n file /et c/ hccn.c onf does not exist.	Check the /et c/ hccn.c onf NIC config uratio n file.	The RoCE NIC is unavai lable.	Snt9B Snt9C
		GPU: basic compo nents abnor mal	GpuEn vironm entSys tem	Major	The nvidia -smi comm and is abnor mal.	Check if the GPU driver is norma l.	The GPU driver is unavai lable.	GPU
				Major	The nvidia-fabric manag er versio n is inconsi stent with the GPU driver versio n.	Check the GPU driver versio n and nvidia- fabric manag er versio n.	The nvidia-fabric manag er cannot work proper ly, affecting GPU usage.	

Event Sourc e	Name space	Event	Event ID	Event Severi ty	Descri ption	Soluti on	Impac t	Suppo rted Model
				Major	The contai ner plug-in nvidia-contai ner-toolkit is not install ed.	Install the contai ner plug- in nvidia- contai ner- toolkit	GPUs cannot be mount ed to Docker contai ners.	
		Local disk mount ing inspec tion	Mount DiskSy stem	Major	The /e tc/ fstab file contai ns invalid UUIDs.	Ensure that the UUIDs in the /et c/ fstab config uratio n file are correct . Other wise, the server may fail to be restart ed.	The disk mount ing proces s fails, preven ting the server from restart ing.	-

Event Sourc e	Name space	Event	Event ID	Event Severi ty	Descri ption	Soluti on	Impac t	Suppo rted Model
		GPU: incorre ctly config ured dynam ic route for Ant series servers	GpuRo uteCo nfigErr or	Major	The dynam ic route of the NIC %s of an Ant series server is not config ured or is incorre ctly config ured. CMD [ip route]: %s CMD [ip route show table all]: %s.	Config ure the RoCE NIC route correct ly.	The NPU netwo rk comm unicati on is abnor mal.	GPU
		NPU: RoCE port not split	RoCEU dpConf igError	Major	The RoCE UDP port is not split.	Check the RoCE UDP port config uratio n on the NPU.	The comm unicati on perfor mance of NPUs is affecte d.	Snt9B Snt9C

Event Sourc e	Name space	Event	Event ID	Event Severi ty	Descri ption	Soluti on	Impac t	Suppo rted Model
		Warni ng of autom atic system kernel upgra de	Kernel Upgra deWar ning	Major	Warni ng of autom atic system kernel upgra de. Old versio n: %s; new versio n: %s.	Syste m kernel upgra de may cause Al softwa re except ions. Check the system updat e logs and preven t the server from restart ing.	The Al softwa re may be unavai lable.	Snt3P 300ID uo Snt9B Snt9C
		NPU enviro nment comm and detecti on	NpuTo olsWar ning	Major	The hccn_t ool is unavai lable.	Check if the NPU driver is norma l.	The IP addres s and gatew ay of the RoCE NIC cannot be configured.	Snt9B Snt9C
				Major	The npu- smi is unavai lable.	Check if the NPU driver is norma l.	NPUs cannot be used.	Snt3P 300ID uo Snt9B Snt9C

Event Sourc e	Name space	Event	Event ID	Event Severi ty	Descri ption	Soluti on	Impac t	Suppo rted Model
				Major	The ascend -dmi is unavai lable.	Check if ToolBo x is proper ly install ed.	ascend -dmi cannot be used for perfor mance analysi s.	Snt9B Snt9C

Installing CES Agent Monitoring Plug-ins

- **Step 1** Create an agency for CES. For details, see **Creating a User and Granting Permissions**.
- **Step 2** Currently, one-click monitoring installation is not supported on the CES page. You need to log in to the server and run the following commands to install and configure the agent. For details about how to install the agent in other regions, see Installing the Agent on a Linux Server.

cd /usr/local && curl -k -O https://obs.cn-north-4.myhuaweicloud.com/uniagent-cn-north-4/script/agent_install.sh && bash agent_install.sh

If the following information is displayed, the installation is successful.

Figure 5-6 Installation succeeded

```
telescope/linux arm64 bin/
telescope/linux arm64 bin/uninstall not root.sh
telescope/linux arm64 bin/telescope
telescope/linux arm64 bin/install.sh
telescope/linux_arm64_bin/install not root.sh
telescope/linux arm64 bin/telescoped
telescope/linux arm64 bin/uninstall.sh
telescope/linux arm64 bin/tools/
telescope/linux arm64 bin/tools/hioadm
telescope/linux arm64 bin/tools/nvme
telescope/linux arm64 bin/tools/storcli64
telescope/linux arm64 bin/tools/sas3ircu
telescope/manifest.json
telescope/telescope-2.4.8-release.json
telescope/linux amd64 bin/
telescope/linux amd64 bin/uninstall not root.sh
telescope/linux amd64 bin/telescope
telescope/linux amd64 bin/install.sh
telescope/linux amd64 bin/install not root.sh
telescope/linux amd64 bin/telescoped
telescope/linux amd64 bin/uninstall.sh
telescope/linux amd64 bin/tools/
telescope/linux amd64 bin/tools/hioadm
telescope/linux amd64 bin/tools/nvme
telescope/linux amd64 bin/tools/storcli64
telescope/linux amd64 bin/tools/sas3ircu
telescope/conf/
telescope/conf/custom conf.json
telescope/windows bin/
telescope/windows bin/uninstall.bat
telescope/windows bin/shutdown.bat
telescope/windows bin/telescope.exe
telescope/windows bin/install.bat
telescope/windows bin/start.bat
telescope/windows bin/getpid.bat
telescope/config/
telescope/config/conf ces.json
telescope/config/logs config.xml
telescope/config/conf.json
Current user is root.
Start to install telescope...
instance type: physical.p7vs.8xlarge.ei
Starting telescope...
Telescope process starts successfully.
```

Step 3 On the Cloud Eye console, choose **Service Monitoring** > **Bare Metal Server** to view the monitoring items. Accelerator card monitoring items are only available after the accelerator card driver is installed on the host.

Figure 5-7 Monitoring page



The monitoring plug-in is now installed. You can view the collected metrics on the UI or configure alarms based on the metric values.

----End

5.5.2 Using DCGM to Monitor Lite Server Resources

Scenario

This section describes how to configure DCGM monitoring on Lite Server to monitor GPU resources.

DCGM is an integrated tool for managing and monitoring large-scale NVIDIA GPU clusters based on Linux. It provides multiple capabilities, including proactive health monitoring, diagnosis, system verification, policy, power and clock management, configuration management, and audit.

Constraints

Only GPU resources can be monitored.

Prerequisites

The driver, CUDA, and fabric-manager software packages have been installed for BMS.

Step 1: Installing Docker

Install the latest Docker using the official script.

curl https://get.docker.com | sh sudo systemctl --now enable docker

Step 2: Installing the NVIDIA Container Toolset

Set the repository address and GPG key.

distribution=\$(. /etc/os-release;echo \$ID\$VERSION_ID) \
 && curl -s -L https://nvidia.github.io/nvidia-docker/gpgkey | sudo apt-key add - \
 && curl -s -L https://nvidia.github.io/nvidia-docker/\$distribution/nvidia-docker.list | sudo tee /etc/apt/
sources.list.d/nvidia-docker.list

Install nvidia-docker2.

sudo apt-get update \
&& sudo apt-get install -y nvidia-docker2

Modify the /etc/docker/daemon.json file as follows:

```
{
    "default-runtime": "nvidia",
    "runtimes": {
        "nvidia": {
            "path": "nvidia-container-runtime",
            "runtimeArgs": []
        }
    }
}
```

Restart Docker daemon.

sudo systemctl restart docker

Step 3: Running DCGM-Exporter

Run DCGM-Exporter in Docker mode.

```
DCGM_EXPORTER_VERSION=3.1.7-3.1.4 && \
docker run -d --rm \
--gpus all \
--net host \
--cap-add SYS_ADMIN \
nvcr.io/nvidia/k8s/dcgm-exporter:${DCGM_EXPORTER_VERSION}-ubuntu20.04 \
-f /etc/dcgm-exporter/dcp-metrics-included.csv
```

□ NOTE

The default metric collection configuration file /etc/dcgm-exporter/dcp-metrics-included.csv of DCGM-Exporter is used. For details about the metric collection objects, see dcgm-exporter. If the collection objects cannot meet the requirements, you can customize an image or mount the image.

Wait for about 1 minute and run the following command to obtain the GPU metrics:

curl localhost:9400/metrics

The output is as follows:

```
# HELP DCGM_FI_DEV_SM_CLOCK SM clock frequency (in MHz).
# TYPE DCGM_FI_DEV_SM_CLOCK gauge
# HELP DCGM_FI_DEV_MEM_CLOCK Memory clock frequency (in MHz).
# TYPE DCGM_FI_DEV_MEM_CLOCK gauge
# HELP DCGM_FI_DEV_MEMORY_TEMP Memory temperature (in C).
# TYPE DCGM_FI_DEV_MEMORY_TEMP gauge
...

DCGM_FI_DEV_SM_CLOCK{gpu="0", UUID="GPU-6ad7ea4c-5517-05e7-0b54-7554cb4374d3"} 1

DCGM_FI_DEV_MEM_CLOCK{gpu="0", UUID="GPU-6ad7ea4c-5517-05e7-0b54-7554cb4374d3"} 4

DCGM_FI_DEV_MEMORY_TEMP{gpu="0", UUID="GPU-6ad7ea4c-5517-05e7-0b54-7554cb4374d3"} 9223372036854578794
...
```

Step 4: Installing Prometheus

Create the **prometheus.yml** file in the **/usr/local/prometheus** directory. The file content is as follows:

```
global:
scrape_interval: 15s # Collection interval
scrape_configs:
- job_name: 'prometheus'
static_configs:
- targets: ['xx.xx.xx.xx:9400'] # Port for obtaining DCGM-Exporter metrics. Replace xx.xx.xx with the IP address of the node where DCGM-Exporter resides.
```

Run Prometheus.

```
docker run -d \
-p 9090:9090 \
-v /usr/local/prometheus/prometheus.yml:/etc/prometheus/prometheus.yml \
prom/prometheus
```

The basic functions of Prometheus are described. For higher requirements, see the **official Prometheus document**.

Step 5: Installing Grafana

Run the latest Grafana.

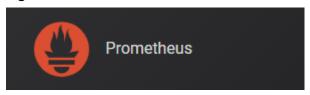
docker run -d -p 3000:3000 grafana/grafana-oss

On the BMS page, open the security group configuration of the node where Grafana is located and add an inbound rule to allow external access to ports 3000 and 9090.

Enter xx.xx.xx.xx.3000 in the address box of the browser to log in to Grafana. The default username and password are both admin. On the configuration management page, add a data source and set the type to **Prometheus**.

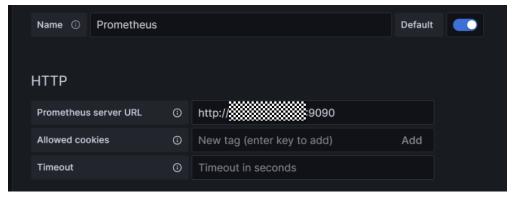
Note: xx.xx.xx is the IP address of the host machine where Grafana is located.

Figure 5-8 Prometheus



Enter the Prometheus IP address and port number in the HTTP URL text box and click **Save&Test**.

Figure 5-9 IP address and port number



The metric monitoring solution is installed, as shown in the following figure.



Figure 5-10 Metric monitoring

The basic functions of Grafana are described. For higher requirements, see the **official Grafana document**.

5.6 Collecting and Uploading NPU Logs

Description

When an NPU is faulty, collect NPU log information by referring to this section. The logs generated in this section are saved on the node and automatically uploaded to the OBS bucket provided by Huawei technical support. Logs are used only for fault locating and analysis. You need to provide the AK/SK for authorization and authentication.

Notes and Constraints

Currently, this function can be used only in CN Southwest-Guiyang1 and CN North-Ulanqab1.

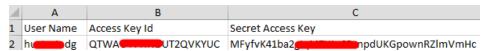
Procedure

Step 1 Obtain the AK/SK, which are used for script configuration, as well as authentication and authorization.

If an AK/SK pair is already available, skip this step. Find the downloaded AK/SK file, which is usually named **credentials.csv**.

The file contains the username, AK, and SK.

Figure 5-11 credential.csv



To generate an AK/SK pair, follow these steps:

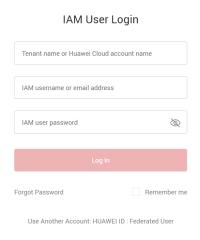
- 1. Log in to the management console.
- 2. Hover the cursor over the username in the upper right corner and choose **My Credentials** from the drop-down list.
- 3. In the navigation pane on the left, choose **Access Keys**.
- 4. Click Create Access Key.

- 5. Download the key and keep it secure.
- **Step 2** Prepare the tenant and IAM accounts for OBS bucket configuration.

Send the prepared information to Huawei technical support. Huawei will configure an OBS bucket policy based on your information. You can upload the collected logs to the corresponding OBS bucket.

After the configuration, the OBS directory **obs_dir** is provided for you to configure subsequent scripts.

Figure 5-12 Tenant and IAM accounts



Step 3 Collect the logs and upload the script.

Modify the value of **NpuLogCollection** in the following script. Replace **ak**, **sk**, and **obs_dir** with the values obtained before. Then, upload the script to the node where NPU logs are to be collected.

```
import json
import os
import sys
import hashlib
import hmac
import binascii
from datetime import datetime
class NpuLogCollection(object):
  NPU_LOG_PATH = "/var/log/npu_log_collect"
  SUPPORT_REGIONS = ['cn-southwest-2', 'cn-north-9']
  OPENSTACK METADATA = "http://169.254.169.254/openstack/latest/meta_data.json"
  OBS_BUCKET_PREFIX = "npu-log-"
  def __init__(self, ak, sk, obs_dir):
     self.ak = ak
     self.sk = sk
     self.obs dir = obs dir
     self.region_id = self.get_region_id()
  def get_region_id(self):
     meta_data = os.popen("curl {}".format(self.OPENSTACK_METADATA))
     json_meta_data = json.loads(meta_data.read())
     meta_data.close()
     region_id = json_meta_data["region_id"]
     if region_id not in self.SUPPORT_REGIONS:
       print("current region {} is not support.".format(region_id))
```

```
raise Exception('region exception')
     return region_id
  def gen_collect_npu_log_shell(self):
     collect_npu_log_shell = "# !/bin/sh\n" \
                      "rm -rf {npu_log_path}\n" \
                      "mkdir -p {npu_log_path}\n" \
                      "echo {echo_npu_driver_info}\n" \
                      "npu-smi info > {npu_log_path}/npu-smi_info.log\n" \
                      "cat /usr/local/Ascend/driver/version.info > {npu_log_path}/npu-smi_driver-version.log
\n" \
                      "/usr/local/Ascend/driver/tools/upgrade-tool --device_index -1 --component -1 --
version > {npu_log_path}/npu-smi_firmware-version.log\n" \
                      "for i in $(seq 0 7); do npu-smi info -t health -i $i -c 0 >> {npu_log_path}/npu-
smi_health-code.log;done;\n"
                      for i in $(seq 0 7);do hccn_tool -i $i -net_health -g >> {npu_log_path}/npu-smi_net-
health.log;done\n"\
                      "for i in $(seq 0 7);do hccn_tool -i $i -link -g >> {npu_log_path}/npu-smi_link.log ;done
\n" \
                      "for i in $(seq 0 7);do hccn_tool -i $i -tls -g |grep switch >> {npu_log_path}/npu-
smi_switch.log;done\n" \
                      "for i in $(seq 0 7);do npu-smi info -t board -i $i >> {npu_log_path}/npu-
smi_board.log; done;\n" \
                      "echo {echo_npu_ecc_info}\n" \
                      "for i in $(seq 0 7);do npu-smi info -t ecc -i $i >> {npu_log_path}/npu-smi_ecc.log;
done;\n" \
                      "for i in $(seg 0 7);do hccn_tool -i $i -optical -g | grep prese >> {npu_log_path}/npu-
smi_present.log;done\n" \
                      "lspci | grep acce > {npu_log_path}/Device-info.log\n" \
                      "echo {echo_npu_device_log}\n" \
                      "cd {npu_log_path} && msnpureport -f > /dev/null\n" \
                      "tar -czvPf {npu_log_path}/log_messages.tar.gz /var/log/message* > /dev/null\n" \
                      "tar -czvPf {npu_log_path}/ascend_install.tar.gz /var/log/ascend_seclog/* > /dev/null
\n" \
                      "echo {echo_npu_tools_log}\n" \
                      "tar -czvPf {npu_log_path}/ascend_toollog.tar.gz /var/log/nputools_LOG_* > /dev/
null" \
        .format(npu_log_path=self.NPU_LOG_PATH,
             echo_npu_driver_info="collect npu driver info.",
             echo_npu_ecc_info="collect npu ecc info."
             echo_npu_device_log="collect npu device log.",
             echo_npu_tools_log="collect npu tools log.")
     return collect_npu_log_shell
  def collect_npu_log(self):
     print("begin to collect npu log")
     os.system(self.gen_collect_npu_log_shell())
     date_collect = datetime.now().strftime('%Y%m%d%H%M%S')
     instance_ip_obj = os.popen("curl http://169.254.169.254/latest/meta-data/local-ipv4")
     instance_ip = instance_ip_obj.read()
     instance_ip_obj.close()
     log_tar = "%s-npu-log-%s.tar.gz" % (instance_ip, date_collect)
     os.system("tar -czvPf %s %s > /dev/null" % (log_tar, self.NPU_LOG_PATH))
     print("success to collect npu log with {}".format(log_tar))
     return log_tar
  def upload_log_to_obs(self, log_tar):
     obs_bucket = "{}{}".format(self.OBS_BUCKET_PREFIX, self.region_id)
     print("begin to upload {} to obs bucket {}".format(log_tar, obs_bucket))
     obs_url = "https://%s.obs.%s.myhuaweicloud.com/%s/%s" % (obs_bucket, self.region_id, self.obs_dir,
     date = datetime.utcnow().strftime('%a, %d %b %Y %H:%M:%S GMT')
     canonicalized_headers = "x-obs-acl:public-read"
     obs_sign = self.gen_obs_sign(date, canonicalized_headers, obs_bucket, log_tar)
     auth = "OBS " + self.ak + ":" + obs_sign
     header_date = '\"' + "Date:" + date +
     header_auth = '\"' + "Authorization:" + auth + '\"'
     header_obs_acl = '\"' + canonicalized_headers + '\"'
```

```
cmd = "curl -X PUT -T " + log_tar + " " + obs_url + " -H " + header_date + " -H " + header_auth + " -H
" + header_obs_acl
     os.system(cmd)
     print("success to upload {} to obs bucket {}".format(log_tar, obs_bucket))
   # calculate obs auth sign
   def gen_obs_sign(self, date, canonicalized_headers, obs_bucket, log_tar):
     http_method = "PUT"
     canonicalized_resource = "/%s/%s/%s" % (obs_bucket, self.obs_dir, log_tar)
     IS_PYTHON2 = sys.version_info.major == 2 or sys.version < '3' canonical_string = http_method + "\n" + "\n" + date + "\n" + canonicalized_headers + "\n" +
canonicalized resource
     if IS_PYTHON2:
        hashed = hmac.new(self.sk, canonical_string, hashlib.sha1)
        obs_sign = binascii.b2a_base64(hashed.digest())[:-1]
        hashed = hmac.new(self.sk.encode('UTF-8'), canonical_string.encode('UTF-8'), hashlib.sha1)
        obs_sign = binascii.b2a_base64(hashed.digest())[:-1].decode('UTF-8')
     return obs sign
   def execute(self):
     log_tar = self.collect_npu_log()
     self.upload_log_to_obs(log_tar)
if __name__ == '__main__':
  npu_log_collection = NpuLogCollection(ak='ak',
                              sk='sk',
                              obs_dir='obs_dir')
  npu_log_collection.execute()
```

Step 4 Run the script to collect logs.

Run the script on the node. If the following information is displayed, logs are collected and uploaded to OBS.

Figure 5-13 Log uploaded

```
Total
            % Received % Xferd
                                Average Speed
                                                 Time
                                                                  Time
                                                                        Current
                                                 Total
                                                         Spent
                                                                  Left
   1778 100
              1778
                                21682
begin to collect npu log collect npu driver info.
collect npu driver info.
collect npu device log.
collect npu tools log.
% Total % Received % Xferd
                                Average
                                                                        Current
                                Dload Upload
                                                 Total
                                                                  Left Speed
```

Step 5 View the uploaded log package in the directory where the script is stored.

Figure 5-14 Viewing the result

5.7 Releasing Lite Server Resources

You can delete or unsubscribe from the resources that are no longer used. For details about how to stop billing, see **Stopping Billing**.

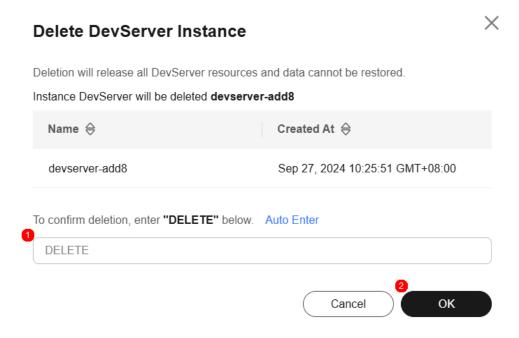
Deleting Lite Server Resources

■ NOTE

Yearly/Monthly Lite Server resources can be deleted only when they fail to be created or are in the error state. In other states, they can only be unsubscribed from.

- 1. Log in to the ModelArts console.
- 2. In the navigation pane on the left, choose AI Dedicated Resource Pools > Elastic Servers.
- 3. Locate the target server in the list and choose > **Delete** on the right. In the displayed dialog box, confirm the information, enter **DELETE**, and click **OK**.

Figure 5-15 Deleting a Server instance



Unsubscribing from a Yearly/Monthly Lite Server

You can unsubscribe from the Lite Server in either of the following ways:

- Method 1: Unsubscribe from a single instance on the ModelArts console.
- Method 2: Unsubscribe from a single or multiple instances in the Billing Center.

Unsubscribing from a single instance on the ModelArts console

- 1. Log in to the ModelArts console.
- In the navigation pane on the left, choose AI Dedicated Resource Pools > Elastic Servers.
- 3. Click View All.

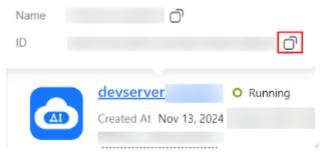
If an agency needs to be configured, contact your account administrator. For details, see **Configuring an Agency for ModelArts**.

- 4. Locate the target BMS in the list and choose > Unsubscribe.
- 5. Confirm the resources to be unsubscribed from and select the reason for unsubscription.
- 6. Confirm the information and select I understand a handling fee will be charged for this unsubscription and After being unsubscribed from, the resources not in the recycle bin will be deleted immediately and cannot be restored. I've backed up data or no longer need the data.
- 7. Click **Confirm** and confirm the resources to be unsubscribed from.
- 8. Click **Unsubscribe** again to unsubscribe from the yearly/monthly resources.

Unsubscribing from a single instance in the Billing Center

- 1. Log in to the ModelArts console.
- In the navigation pane on the left, choose AI Dedicated Resource Pools > Elastic Servers.
- 3. Hover the cursor over the node name and copy the ID of the instance to be unsubscribed from.

Figure 5-16 Copying the instance ID



Ⅲ NOTE

The resource ID bound to the Server purchase order is the Server ID, which is different from the BMS/ECS ID encapsulated in the Server product. To unsubscribe from Server, log in to the ModelArts console and choose AI Dedicated Resource Pools > Elastic Servers on the left.

4. Choose **Billing** from the top menu bar. In the navigation pane on the left, choose **Orders** > **Unsubscriptions and Returns/Exchanges**.

Figure 5-17 Unsubscriptions and Returns/Exchanges

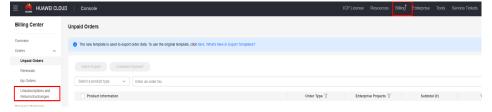


- 5. Search for the instance ID, confirm the information, and click **Unsubscribe from Resource** in the **Operation** column.
- 6. Confirm the resources to be unsubscribed from and select the reason for unsubscription.
- 7. Confirm the information and select I understand a handling fee will be charged for this unsubscription and After being unsubscribed from, the resources not in the recycle bin will be deleted immediately and cannot be restored. I've backed up data or no longer need the data.
- 8. Click **Confirm** and confirm the resources to be unsubscribed from.
- 9. Click **Unsubscribe** again to unsubscribe from the yearly/monthly resources.
- Unsubscribing from multiple instances in the Billing Center
- 1. Log in to the ModelArts console.
- In the navigation pane on the left, choose AI Dedicated Resource Pools > Elastic Servers.
- 3. Record the IDs of instances to be unsubscribed from.

If an agency needs to be configured, contact your account administrator. For details, see **Configuring an Agency for ModelArts**.

4. Choose **Billing** from the top menu bar. In the navigation pane on the left, choose **Orders** > **Unsubscriptions and Returns/Exchanges**.

Figure 5-18 Unsubscriptions and Returns/Exchanges



- 5. Select the target instances and click **Batch Unsubscribe**.
- 6. Confirm the resources to be unsubscribed from and select the reason for unsubscription.
- 7. Confirm the information and select I understand a handling fee will be charged for this unsubscription and After being unsubscribed from, the resources not in the recycle bin will be deleted immediately and cannot be restored. I've backed up data or no longer need the data.
- 8. Click **Confirm** and confirm the resources to be unsubscribed from.
- 9. Click **Unsubscribe** again to unsubscribe from the yearly/monthly resources.